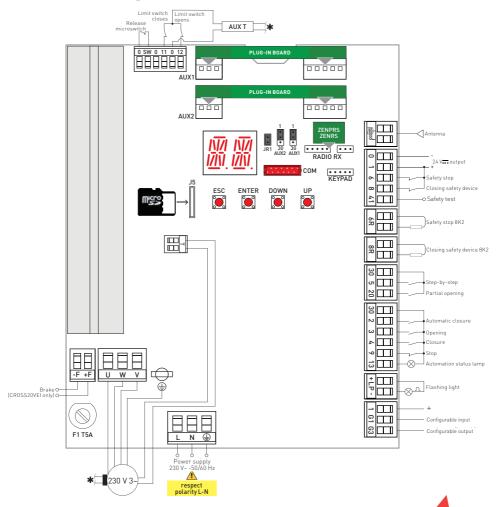






## Ditec LCU43A - LCU43B

Installation manual for control panel for the CROSS20VEI and CROSS35VEI automation systems with 230 V 3~ motor



#### Contents

	l safety precautions for the user	
	l safety precautions	
	claration of Conformity	
1.	Safety functions	
2.	Technical specifications	
2.1	Applications	9
3.	Installation and electrical connections	.10
4.	Standard installation	
4.1	Standard installation connections diagram	
<b>5.</b> 5.1	Commands and safety devices Safety inputs	.14
5.2	Limit switch inputs	
6.	Outputs and accessories	
7.	Jumper setting	
8.	Using menus	.18
8.1	Switching the display ON and OFF	.18
8.2	Navigation keys	
9.	Setting up product for first use	
9.1	Wizard configuration menu (WZ)	.22
9.2	Basic start-up example	
<b>10.</b> 10.1	Frequently used menu sequences  Enabling the configurations	
10.2	Adding remote controls	.25
10.3	Configuring the NC contact safety devices	.25
10.4 10.5	Configuring the resistive safety edges	
11.	Configuration and settings menu	
11.1	Main menu	.27
11.2	Second level menu - AT (Automatic Configurations)	.28
11.3	Second level menu - BC (Basic Configurations)	.29
11.3.1 11.4	Additional BC level parameters that can be configured (available with $\begin{picture}(1,0)\pu\line(0,0)\pu\line($	30 31
	ALES LEAL L. C. L.C. T. C. L.C. T. D. T. D. D. L.D.	.01
11.4.1 11.5	Additional BA level parameters that can be configured (available with $\overrightarrow{H} \overrightarrow{I} \rightarrow \overrightarrow{H} \overrightarrow{H}$ enabled)	32 .35
11.5.1	Additional configurable R0 level parameters available with $\overrightarrow{P} \overrightarrow{I} \rightarrow \overrightarrow{P} \overrightarrow{P}$ enabled	24
11.6	Second level menu - SF (Special Functions)	.37
11.6.1	Additional configurable SE level parameters available with $\mathbf{P} \to \mathbf{P} \to \mathbf{P}$ enabled	.38
11.7	Additional configurable SF level parameters available with $\overrightarrow{\textbf{AT}} \rightarrow \overrightarrow{\textbf{PR}}$ enabled	.40
11.7.1	Additional configurable CC level parameters available with R. T. A. P. enabled	/ <sub>1</sub> ∩
11.8	Second level menu - EM (Energy Management)	.41
11.9	Second level menu - AP (Advanced Parameters)	.41
11.9.1	Second level menu - EM (Energy Management) Second level menu - AP (Advanced Parameters) Additional AP level parameters that can be configured (available with $\overrightarrow{P} \overrightarrow{T} \rightarrow \overrightarrow{P} \overrightarrow{P}$ enabled)  Diagnostics	42
<b>12.</b> 12.1	Data Logging integrated in the card	.45 //5
12.1.1	Alarm counter	45
12.1.2	Alarm log	
12.1.3 12.2	Exporting information on the microSD	
13.	Examples of application for parallel automations	
13.1	Examples of application for interlocked automations with one-way or two-way transit, without presence detection	.50
13.2	Examples of application for interlocked automations with one-way transit, with presence detection	
<b>14.</b> 14.1	Signals visualised on the display  Display of automation status	
14.1	Display of safety devices and commands	.54
14.2.1	Messages visible if G1= SY	55
14.3 <b>15.</b>	Visualisation of alarms and faults	
16.	Maintenance	
17	Profite for the second	.00

Key

This symbol indicates instructions or notes regarding safety, to which special attention must be paid.

This symbol indicates useful information for the correct operation of the product.

Factory settings

# IP2336EN

## General safety precautions for the user



WARNING! Important safety instructions • Follow these instructions carefully. Failure to respect the information given in this manual may lead to serious injury to people or damage to the device • Keep these instructions for future reference WARNING: disconnect the power supply before carrying out any cleaning or maintenance task This manual, and those relating to accessories, can be downloaded from the website www.ditecautomations.com

These precautions are an integral and essential part of the product and must be supplied to the user. Read them carefully as they contain important indications for safe installation, use and maintenance • Keep these instructions and pass them on to anyone else who uses the system • This device must only be used for the specific purpose for which it was designed; any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use • Do not work near hinges or moving mechanical parts. Do not enter within the operating range of the motorised door or gate while it is moving. Do not obstruct the movement of the motorised door or gate, as this may lead to a dangerous situation • Only lock and release the door wings with the motor switched off. Do not enter within the operating range of the motorised door or gate • When working in "hold-to-run" mode, the relative command devices must be positioned so as to ensure a direct, complete view of the door or gate during operations, far away from moving parts, at a minimum height of 1.5 m, and not accessible by the public • The motorised door or gate may be used by children over the age of 8 and people with a reduced physical, sensorial or mental capacity, or without the necessary knowledge and experience, as long as they are supervised or have received instructions regarding safe use and the inherent risks • Children

must be supervised to ensure they do not play with the device itself. nor play or remain within the operating range of the motorised door or gate. Keep the remote controls and/or any other control device out of the reach of children, to avoid any accidental activation of the motorised door or gate • The cleaning and maintenance tasks that are the responsibility of the user must not be carried out by unsupervised children • In the event of a fault or malfunctioning of the device, disconnect the power supply switch; do not attempt to make any repairs or intervene directly in any way. Any repairs or technical interventions must be carried out by qualified personnel. Failure to respect the indications above may lead to dangerous situations • To ensure the system works efficiently and correctly, it is essential to respect the manufacturer's indications and have scheduled maintenance on the motorised door or gate carried out by qualified personnel. In particular, regular checks must be made to ensure all the safety devices are working properly • Written evidence of all installation, maintenance and repair tasks must be made available to the user.

## General safety precautions



WARNING! Important safety instructions.

Follow these instructions carefully. Failure to respect the information given in this manual may lead to serious injury to people or damage to the device.

Keep these instructions for future reference.

This manual, and those relating to accessories, can be downloaded from the website www.ditecautomations.com

This installation manual is intended for qualified personnel only
• The installation, electrical connections and adjustments must
be made by qualified personnel, using Good Working Methods
and respecting the regulations in force • Read these instructions
carefully before beginning to install the device. Incorrect installation may be a source of danger • Before beginning the installation,
make sure the device is in good condition •

🕰 Dispose of the packaging materials (plastic, polystyrene, etc.) responsibly; keep them out of the reach of children, as they are a potential source of danger • Do not install the device in an explosive atmosphere or area: the presence of gas or inflammable fumes are a serious safety hazard • Make sure the place of use is compatible with the working temperature range indicated in the technical specifications • Before installing the motorisation device, check that the existing structure and the support and quide elements meet the robustness and stability requisites; check the stability and smooth operation of the guided part, and make sure there is no risk of it slipping out of its track or tipping over. Make all the structural modifications necessary in order to create safety clearance and to guard or isolate all the crushing, shearing, trapping and general danger areas. The motorisation device manufacturer is not responsible for failure to observe Good Working Methods when building the frames to be motorised, nor for any deformation during use • When installing the safety devices (photocells, safety edges, emergency stops, etc.), the current standards and directives must be taken into consideration along with Good Working Methods criteria, the place of installation, the system operating logic and the forces developed by the motorised door or

gate • The safety devices must protect any possible crushing, shearing, trapping or general danger areas of the motorised door or gate. Apply the legally required signs to identify the danger areas • The motorised door or gate ID data must be visible on every installation • Before connecting the electricity supply, make sure the mains power supply corresponds to the plate data. An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply. Check there is a suitable circuit breaker and overcurrent cut-out upstream from the electrical system, to respect Good Working Methods and the regulations in force • When necessary, connect the motorised door or gate to an earth system that meets the current safety regulations • Before leaving the system in the hands of the end user, make sure the automation is properly adjusted to satisfy the operating and safety requisites, and that all the command, safety and manual release devices are working correctly.

When maintenance and repair work needs to be carried out, disconnect the electricity supply before opening the cover to access the electrical parts • The protective cover on the automation must only be removed by qualified personnel • To carry out those operations involving access to the inside of the control panel in the presence of power, such as may be the adjustment of operating parameters, it is mandatory to wear personal protective equipment in accordance with the law for live operation, especially safety dielectric gloves approved at least as Class 00 (500 V) according to EN 60903.

The electronic parts must be handled using earthed antistatic conductive arms. The motorisation device manufacturer disclaims all responsibility if components incompatible in terms of safety and good operation are installed • Only original spare parts must be used when repairing or replacing the device • The installer must provide the system user with all the information regarding the automatic, manual and emergency operation of the motorised door or gate, along with the operating and safety instructions.

## EU Declaration of Conformity

We:

ASSA ABLOY Entrance Systems AB Lodjursgatan 10 SE-261 44 Landskrona

Sweden

Declare under our sole responsibility that the types of equipment with names:

Ditec LCU43A, Ditec LCU43B Control panel for CROSS20VEI and CROSS35VEI automation systems with 230 V  $3\sim$  motor

Comply with the following directives and their amendments:

2014/35/EU Low Voltage Directive (LDV)

2014/30/EU Electromagnetic Compatibility Directive (EMCD)

2014/53/EU RED Directive;

2011/65/EU Restriction of hazardous substances (RoHS 2)

2015/863/EU Restriction of hazardous substances (RoHS 2 Amendment)

Harmonized European standards that have been applied:

EN 61000-6-3:2007 + A1:2011 + AC:2012

FN 61000-6-2:2019

EN 60335-1:2012 + AC:2014 + A11:2014 + A13:2017 + A1:2019 + A14:2019 + A2:2019

EN 60529:1991 + A1:2000 + A2:2013 + AC:2016

EN 62233:2008 + AC:2008 EN ISO 13849-1:2015

Other standards or technical specifications that have been applied:

IEC 60335-1:2010 + C1:2010 + C2:2011 + A2:2013 + C1:2014 + A2:2016 + C1:2016

EN 12453:2017

The manufacturing process ensures the compliance of the equipment with the technical file.

Responsible for technical file:

Matteo Fino BSP Ind channel & Gate Automation Ditec S.p.A. Largo U. Boccioni, 1 21040 Origgio (VA)

Italy

Signed for and on behalf of ASSA ABLOY Entrance Systems AB by:

Place Date Signature Position

Origgio 2022-09-30 Matteo Figo Head of Ind channel & Gate Automation

Totles for

IP2336EN

## UK Declaration of Conformity

We:

ASSA ABLOY Entrance Systems AB Lodjursgatan 10 SE-261 44 Landskrona Sweden

Declare under our sole responsibility that the types of equipment with names:

Ditec LCU43A, Ditec LCU43B Control panel for CROSS20VEI and CROSS35VEI automation systems with 230 V 3~ motor

Comply with the following directives and their amendments:

- Supply of Machinery (Safety) Regulations 2016
- Electrical Equipment (Safety) Regulations 2016
- Electromagnetic Compatibility Regulations 2016
- Radio Equipment Regulations 2017
- The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 (RoHS)

Harmonized European standards that have been applied:

FN 61000-6-3:2007 + A1:2011 + AC:2012

FN 61000-6-2:2019

EN 60335-1:2012 + AC:2014 + A11:2014 + A13:2017 + A1:2019 + A14:2019 + A2:2019

EN 60529:1991 + A1:2000 + A2:2013 + AC:2016

EN 62233:2008 + AC:2008

FN ISO 13849-1-2015

Other standards or technical specifications that have been applied:

IEC 60335-1:2010 + C1:2010 + C2:2011 + A2:2013 + C1:2014 + A2:2016 + C1:2016

FN 12453-2017

The manufacturing process ensures the compliance of the equipment with the technical file.

Responsible for technical file:

Matteo Fino BSP Ind channel & Gate Automation Ditec S.p.A. Largo U. Boccioni, 1 21040 Origgio (VA) Italy

Signed for and on behalf of ASSA ABLOY Entrance Systems AB by:

Place Date Signature Position 2022-09-30 Origgio

Mattes fin

Matteo Fino Head of Ind channel & Gate Automation

## 1. Safety functions

The Ditec LCU43A and LUC43B control panel has the following safety functions:

- obstacle recognition with force limiting;

The maximum response time of the safety functions is 0.5s. The reaction time to a faulty safety function is 0.5s.

The safety functions comply with the standards and performance level indicated below:

EN ISO 13849-1:2015 Category 2 PL=c EN ISO 13849-2:2012

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

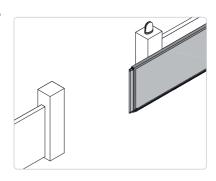
## 2. Technical specifications

	LCU43A		LCU43B
Power supply	230 V~, -10%/ +10%, 50/60 Hz		
Power absorption	3,5 /	A	4,0 A
Fuse		F1=	T5A
Motor output	Inverter 230 V 3-	~; 1 x 6 A max	Inverter 230 V 3~; 1 x 9 A max
Permanent power supply to accessories 0-30	24 V== 0,15 A	WARNIN	G: in any case, the total of
Power supply to accessories 0-1	24 V= 0,5 A (continuous)	acces:	sories 0-30 and 0-1 must not d 0.5 A
Ambient temperature	-20 °C - +55 °C		
Storable radio codes	100/200 [see R0 $\rightarrow$ MU $\rightarrow$ 10/20]		
Radio frequency	433,92 MHz (cod. ZENRS) 868,35 MHz (cod. ZENPRS) ZENRS receiver module incl ZENPRS optional		ENRS receiver module included, ENPRS optional
Protection rating of the box	refer to the technical data sheet for the CROSS20VEI automation system		refer to the technical data sheet for the CROSS35VEI automation system
Product size	187x261x103 mm 238x357x120 mm		238x357x120 mm



**NOTE**: The given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.

#### 2.1 Applications



#### 3. Installation and electrical connections

- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cut-out upstream of the electrical system.
- For the power supply, use a H05RN-F 3G1.5 type electric cable. Connect it to terminals L (brown), N (blue), ( (yellow/green) inside the automation.
- Pass the power supply cable through the supplied ferrite filter as shown in figures 3.1 and 3.2.

**NOTE:** the maximum permitted wire section is AWG14 (2mm²).

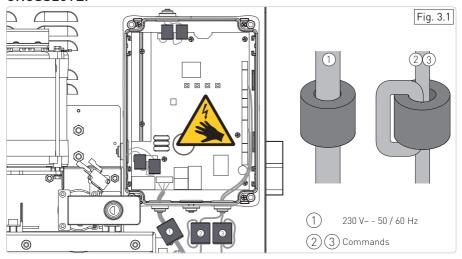
- Unsheathe the power supply cable in line with the terminal.
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the connections with the terminal have been made.



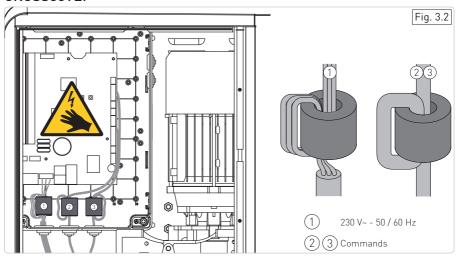
The connections to the mains power supply and to any possible low voltage wires (230 V) in the section outside the electronic panel must be made on an independent channel separated from the connections to the command and safety devices (SELV = Safety Extra Low Voltage). The corrugated tubes must enter the electronic panel by a few centimetres via the slots on the base box.

- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains power wires (230 V) and the accessory wires (24 V) are separated.
- Pass the control cables through the ferrite filters as in figures 3.1 and 3.2.
- The cables must have dual insulation. Unsheathe them in line with the relative connection terminals.

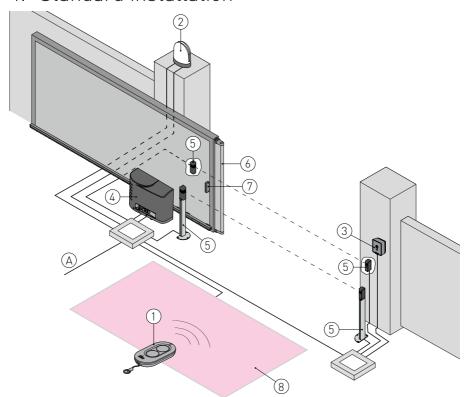
#### CROSS20VEI



#### CROSS35VEI

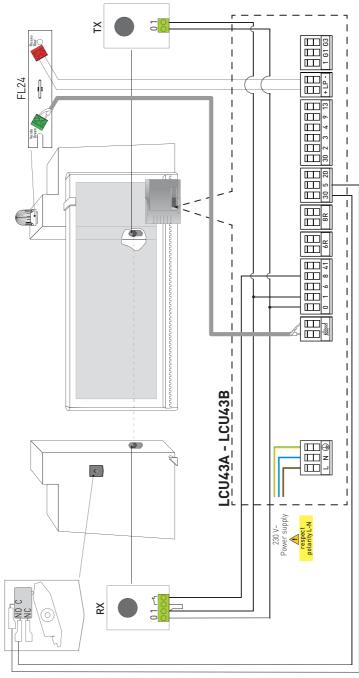


## 4. Standard installation



Ref.	Code	Description	Cable
1	ZEN	Transmitter	/
2	FLM FL24	Flashing light 230 V Flashing light 24 V	2 x 1 mm²
2		Antenna (integrated in the flashing light)	RG-58 coax cable (50 Ω)
	AXK5	Key selector switch	4 x 0.5 mm <sup>2</sup>
3	AXR7 AXK4	Transponder Digital combination wireless keypad	/
4	CROSS20VEI CROSS35VEI	Actuator (motor) 230 V 3~	3G x 1.5 mm²
Α		Connect the power supply to a certified-compliant omnipo included) with a contact opening distance of at least 3mm. Co mains must be via an independent conduit, separated from the to the command and safety devices.	nnection to the
5	LIN2 LIN2B AXP2 LAB4	Photocells Photocells Photocells Photocells IP55	4 x 0.5 mm²
6	SOFAP20 SOF2M20-SOF3M20 SOFA15-SOFA20-SOFA25	Safety edge Safety edge Safety edge	2 x 0,5 mm² min
7	GOPAV	Radio system for sensitive edges	/
8	LAB9	Magnetic loop detector	2 x 1,5 mm <sup>2</sup>

## 4.1 Standard installation connections diagram



P2336EN

## 5. Commands and safety devices



You are advised to read paragraph 11 for all the details about the possible adjustments



**WARNING**: terminal 30 (common positive for commands) has the same functions as terminal 1 and for this reason, the commands visible on the display are indicated with 1-5, 1-3, 1-4, etc. However, unlike terminal 1, it is also active when the control panel is in stand by  $\mathbf{E} \supset \mathbf{D} \mathbf{N}$ .



**WARNING**: make a jumper for all NC contacts if not used, or deactivate them via the relative menu. Terminals with the same number are equal.

	Command		Function	Description
30 <b>—</b>	2	NO	AUTOMATIC CLOSURE	Permanent closing of the contact enables automatic closure if $\square$ $\rightarrow$ 1- 2
			OPENING	When selecting $\mathbb{I} \longrightarrow \mathbb{I} \longrightarrow \mathbb{I} \longrightarrow \mathbb{I}$ , the closure of the contact activates an opening operation.
30 —	3	NO	STEP-BY-STEP	When selecting $\P \ \to \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $
30 <b>—</b>	4	NO	CLOSURE	Closing of the contact activates a closing operation.
30 -	5	NO	STEP-BY-STEP	When selecting $\mathbb{R} \longrightarrow \mathbb{C} \longrightarrow$
			OPENING	When selecting $\exists \vdash \rightarrow \vdash \rightarrow \vdash \rightarrow$ , the closure of the contact activates an opening operation.
1 —	<u>t</u> 6	NC	SAFETY STOP	The opening of the safety contact stops and prevents any movement. <b>NOTE</b> : to set different safety contact functions, refer to the settings of parameter $P \rightarrow M$ .
1 —	<b>——</b> 8	NC	CLOSING SAFETY DEVICE	The opening of the safety contact triggers a reversal of the movement [reopening] during the closing operation. With $\exists \mathbb{C} \to S \ \bigcirc \to \ \bigcirc \ N$ , the opening of the contact prevents any operation when the automation is stationary. With $\exists \mathbb{C} \to S \ \bigcirc \to \ \bigcirc \ F$ , the opening of the contact only prevents the closing operation when the automation is stationary.
1 —	6 8	NC	CLOSING/ OPENING SAFETY DEVICE	The opening of the safety contact stops and prevents any movement. NOTE: operation corresponds to that of contact 1-6 with $P \to SM \to DS$ .
30 –	t_ 9	NC	STOP	The opening of the safety contact causes the current operation to stop. If $\mathbb{RP} - \mathbb{R9} = \mathbb{9P}$ , automatic closure is disabled when contact 30-9 recloses. If $\mathbb{RP} - \mathbb{R9} = \mathbb{9T}$ , automatic closure remains enabled when contact 30-9 recloses.
30 —	9	NO	HOLD-TO-RUN COMMAND	When selecting \$\mathbb{RP} \rightarrow \mathbb{RS} \rightarrow \mathbb{HR}\$, the opening of contact 30-9 enables the "operator present" function: - opening with hold-to-run 30-3 - closure with hold-to-run 30-4 \$\mathbb{NOTE}\$: any safety devices, automatic closure and plug-in board in the AUX slot are all disabled.
30 —	20	N0	PARTIAL OPENING	The closure of the contact activates a partial opening operation. Once the automation stops, the partial opening control performs the opposite operation to the one performed before the stop.

## 5.1 Safety inputs

Command		Function	Description
1 6	NC	SAFETY STOP	When selecting $\begin{tabular}{l} P \rightarrow \begin{tabular}{l} D \rightarrow \begin{tabular}{l} M \end{tabular}, connect the output contact of the safety device to terminals 1-6 on the control panel (in series with the photocell output contact, if installed).$
1 8	NC	CLOSING SAFETY DEVICE	When selecting $\begin{tabular}{l} P \rightarrow \begin{tabular}{l} B \rightarrow \begin{tabular}{l} Y \end{tabular}, connect the output contact of the safety device to terminals 1-8 on the control panel (in series with the photocell output contact, if installed).$
1 6	NC	CLOSING/ OPENING SAFETY DEVICE	When selecting $P \to B \to S H$ , connect the output contact of the safety device to terminals 1-6-8 on the control panel (in series with the photocell output contact, if installed). If $B \to S H$ , $B \to B H$ cannot be $P H$ or $S H$ .
GR	R=8,2 kΩ -10%/ +10%	OPENING RESISTIVE SAFETY EDGE	With $\Pi P \Rightarrow G$ R confirmed by $N \mathbb{O}$ , a short circuit or open circuit state of the resistor triggers a stop with disengagement and movement direction reversal on the basis of the value set for parameter $G$ R.
BR 8R	R=8,2 kΩ -10%/ +10%	CLOSING RESISTIVE SAFETY EDGE	With $\Pi P \rightarrow \Pi R$ confirmed by $N \Pi$ , a short circuit or open circuit state of the resistor triggers a stop with disengagement and movement direction reversal on the basis of the value set for parameter $\Pi R$ .

## 5.2 Limit switch inputs

Command		Function	Description
011	NC	CLOSING LIMIT SWITCH	Extra low voltage limit switch logic contact.
012	NC	OPENING LIMIT SWITCH	Extra low voltage limit switch logic contact.

## 6. Outputs and accessories

Output	Value of accessories	Description
- + 	24 V <del></del> / 0.5A	Power supply to accessories.  Output for power supply to external accessories.  NOTE: the maximum power absorption of 0.5 A corresponds to the sum of all terminals 1.  The "gate open" indicator light (30-13) is not calculated in the 0.3A indicated above. The maximum value to be considered is 3W.
30 2 3 4 9 13	24 V <del></del> / 3W	Automation status lamp. For the operating mode of output 30-13, refer to the selection
1 G1G3	10 mA max	G1 - General Purpose Input  Operating of the G1 input can be selected from the menu    G3 - General Purpose Output  Operating of the G3 output depends on the type of G1 input selection.  SY - If    G3 - SY, G3 acts as a sync output for parallel or interlocked automations.  ES - Energy Saving mode is not available with this configuration.  41 - If the safety test    G3 acts as an output for the safety device test.  30 - G3 acts as a permanent positive at max 24 V 10 mA, to be connected with the NO contact to G1 (opening and/or step-by-step).
AUX 1 AUX 2	SOFA1-SOFA2 GOPAVRS LAB9 BIXR2 BIXPR2 LAN7S	The control panel has two slots for plug-in command and safety boards. The action of the control card can be selected using $\Box \to AM$ for AUX1 and $\Box \to AM$ for AUX2. When using slot-in radio boards, remove the RDX module. The display will show $AV$ .  WARNING: the plug-in board must be inserted and removed with the power supply disconnected.
	ANTENNA	Input for GOL148REA external antenna or rigid wire antenna supplied according to the operating frequency of the receiver module used.
+LP-	FLM - FL24 24 V <del></del> / 15W	Flashing light. The pre-flashing settings can be selected from the third level menu $\PP \to \square$ and/or $\PP \to \square$ . To modify the operating mode of the LP output, refer to the selection $\PP \to \square$ .
RADIO RX	ZENRS ZENPRS	The control panel has a housing for modules of the ZENRS radio receiver type (433.92 MHz). Can be replaced with a module of the ZENPRS radio receiver type (868.35 MHz). The operating mode is selected via $ \mathbb{B} \mathcal{L} \to \mathcal{R} \mathcal{M} $ . When using slot-in radio boards, remove the RDX module. The display will show $ \mathbb{R} \mathcal{L} $ . WARNING: the modules must be inserted and removed with the power supply disconnected.
Micro	MicroSD	The control panel manages microSD cards for updating the firmware and for diagnostics and configuration storage/recovery via the in commands

Output	Value of accessories	Description
сом	BIXMR2	$ \begin{array}{l} \text{COM} \text{ - Allows the operating configurations to be saved using the function } \text{SF} \\ \rightarrow \text{SV}. \\ \text{The saved configurations can be recalled using the function } \text{SF} \rightarrow \text{RC}. \\ \text{COM} \text{ - The storage module allows the remote controls to be saved in the memory.} \\ \text{If the control panel is replaced, the storage module being used can be inserted in the new control panel.} \\ \hline \qquad & \text{WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction.} \\ \end{array} $
KEYPAD	FUTURE USE	

## 7. Jumper setting

Jumper	Description	OFF •	0N 💽
JR1	Display mode selection.	Display mode The values and parameters present can be only displayed.	Maintenance mode The values and parameters present can be displayed and modified. Activated maintenance mode is indicated by the permanent lit on of the right-hand point on the display.
Jumper	Description	1 30	1 30
AUX1	Selection of power supply - auxiliary card 1.	AUX1 powered from 0-1.	AUX1 powered from 0-30.
AUX2	Selection of power supply - auxiliary card 2.	AUX2 powered from 0-1.	AUX2 powered from 0-30.

## 8. Using menus



**NOTE**: pressure on the keys may be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

#### 8.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:

ENTER

• press the key



• the display functioning check starts



• the first level menu is displayed

The procedure to switch off the display is as follows:

• press the key

 $\mbox{{\bf NOTE}}:$  the display switches off automatically after 60 s of inactivity.

#### 8.2 Navigation keys

- UP and DOWN keys: for scrolling through level one or two menus and through the list of possible values for a specific parameter.
- ENTER key: accesses the next menu level or the list of possible values for a menu parameter. Press and hold to confirm selection of the currently displayed parameter value.
- ESC key: go back to previous step in navigation.
- Simultaneous pressing of the keys **UP** and **ENTER** performs an opening command.



• Simultaneous pressing of the keys **DOWN** and **ENTER** performs a closing command.

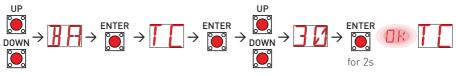


<u>Simultaneous</u> pressing of the keys **UP** and **DOWN** performs a POWER RESET command. (interruption of the power supply and restart of the automation).

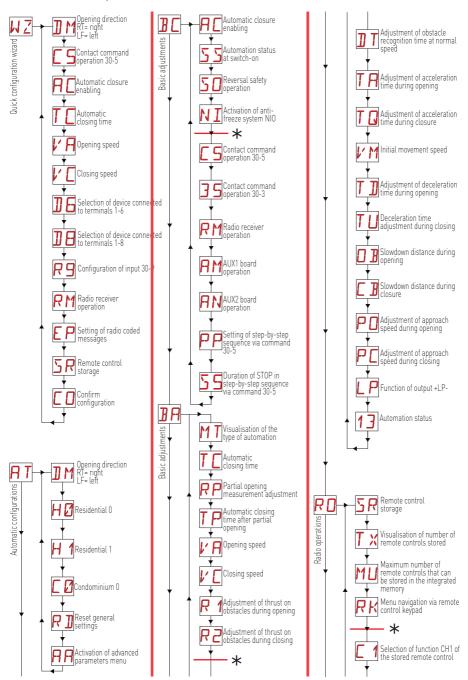


- Hold down the **UP** or **DOWN** key to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

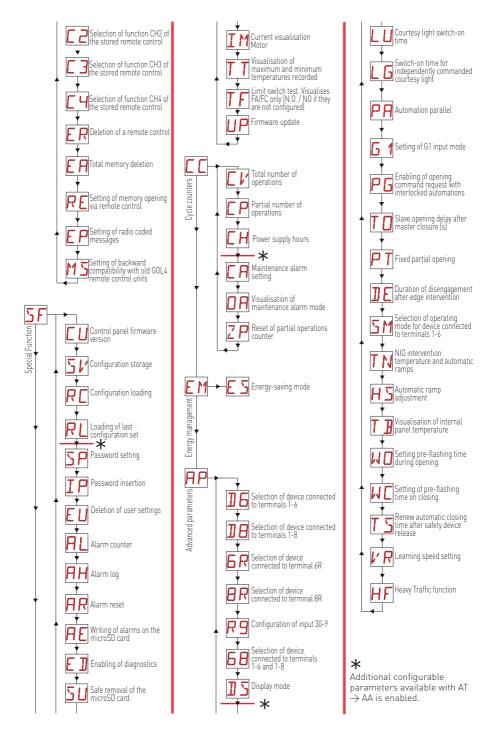
Example: setting of 30 seconds for TC parameter.



#### 8.3 Menu map







## 9. Setting up product for first use

Use the WIZARD (WZ) wizard or the level two AT menu (automatic configuration) to set the product up rapidly with a quick configuration procedure [see parag. 9.2].

For detailed, customised configuration, use the main menus **BC**, **BA**, **RO**, **SF**, **CC**, **EM**, **AP** 

#### 9.1 Wizard configuration menu (WZ)

#### To access the WZ quick configuration wizard menu:

Hold down the ENTER button for 2 seconds.

Once the message OK stops flashing, the first menu parameter:



#### To set a parameter:

- 1. Press ENTER to access the configuration items.
- 2. Scroll UP/DOWN the possible options.
- To confirm, press the ENTER button for 2 seconds. The selected value flashes and when it has finished, the next parameter appears.



#### List of parameters in WIZARD menu:

	Display	Description
	IM	<ul> <li>DM - Selection of the direction mode</li> <li>LF: opening towards left direction (output axis turns clockwise during opening)</li> <li>RT: opening towards right direction (output axis turns counterclockwise during opening)</li> </ul>
WZ - Quick configuration wizard	۵5	C5 - Operation of command associated with contact 30-5  • 1-5: step-by-step (default) • 1-3: opening • NO: none • LG: courtesy light
	AC	AC - Enabling of automatic closure  • ON: enabled (default)  • OF: disabled  • 1-2: dependent on input 1-2  • hR: push-to-operate "dead man" closure (independently of setting of parameter R9)  • hr: push-to-operate "dead man" closure, obliged until complete closure (independently of setting of parameter R9)  • NOTE: in hr mode if the closure command is removed before reaching the closed position limit switch, the door/gate re-opens automatically.
Quick c	T[	TC - Setting of automatic closing time [seconds] [NOTE: only viewable visible if AC = ON was selected in previous step] • from 0" to 59" with intervals of 1 second. • from 1 (default) to 2' with intervals of 10 seconds.
) - ZM	VΑ	VA - Opening speed. [cm/s] CROSS20VEI 10 - Minimum. 20 - Default. 30 - Maximum. CROSS35VEI 10 - Minimum. 20 - Default. 25 - Maximum.

	l'	, [	VC - Closing speed. [cm/s] CROSS20VEI 10 - Minimum.
			30 - Maximum. CROSS35VEI
			10 - Minimum. 25 - Maximum.
			D6 - Selection of device connected to terminals 1-6 • N0: none.
ard	I	5	<ul> <li>SE: safety sensing edge (if contact 1-6 opens, 10 cm disengagement is implemented after stop).</li> <li>S41: safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection</li></ul>
iza			D8 - Selection of device connected to terminals 1-8
	T	$\overline{}$	NO: none. SE: safety edge.
U O	ij	ᆸ	• S41: safety edge with safety test.
ä			PH: photocells.  P41: photocells with safety test.
<u> </u>			R9 - Configuration of input 30-9
igi			<ul> <li>NO: disabled.</li> <li>9P: open state of an input triggers permanent stop (default).</li> </ul>
Juc	L		• 9T: open state of an input triggers temporary stop. Once contact closes, automatic closure time (if enabled) is activated.
υ			HR: automation operates in "operator present" mode if input is open.
- Quick configuration wizard	R	11	RM - Radio receiver operation  • 1-5: opening (default)  • 1-3: step-by-step
Ø			EP - AES (Encrypted Packet) reception setting
- 7	F	P	If the possibility to receive coded messages is enabled, the control panel will be compatible with remote controls of the "AES-128 Encrypted" type.
$\geq$	_	•	• <b>0N</b> : enabled • <b>0F</b> : disabled
			SR - Remote control storage
	5	R	When you press ENTER, SR starts to flash and you can associate the desired buttons. Once OK is displayed, SR starts to flash again and you can associate the next button. To quit, press ESC or ENTER for 2 seconds and go on to the next item.
			NOTE: if NO flashes on the display, the remote control may already be stored.
			CO - Save Wizard settings
			Here you can save the parameters that have previously been set.     YS: to save and perform a card RESET
	L	_ 니	NO: to quit without saving and go back to a blank screen (central part only)
			NOTE: the message CO and YS/NO sub-menus flash constantly.

#### To save the configuration:

In the CO parameter select YS (yes) and press the ENTER button for 2 seconds.

After saving, a board POWER RESET cycle is performed automatically:

for 2 sec.  $\bigcirc$ 

#### To quit without saving changes:

Select the option NO for the parameter CO and then press and hold ENTER for 2 seconds



Or: from any main parameter, press the ESC button for 2 seconds. Example:



#### NOTES:

- The set values are only stored on the card if they are saved using the CO parameter.
- The parameter CO and the YS/NO options flash constantly.
- After confirming a configuration parameter, the wizard moves on automatically to the next parameter.
- The UP/DOWN buttons may be used at any time, however, to scroll through parameters.
- There is no time limit for selecting and the wizard will not quit automatically.

#### 9.2 Basic start-up example



WARNING: the system must have sufficiently robust mechanical end stops and limit switches must be installed. The limit switches must be configured in stop mode.



WARNING: if the control panel is used to replace an identical control panel which is faulty, the last automation configuration can be recovered by inserting the old control panel storage module into the new control panel and loading the last set configuration using the menu sequence  $\overline{SF} \rightarrow \overline{FL}$ 



WARNING: before using the automation, make sure that the operating forces of the gate wings comply with the EN 12453:2017 standard and subsequent revisions.

- 1. Turn on the power.
- quired for the application. Make sure that the opening direction parameter is correct (parameter 7 M
- 3. Make a jumper for the safety contacts 1-6, 1-8 and 1-9, if they are not deactivated via menu parameters  $| \downarrow \downarrow 7 \rightarrow | ] [ 6 ], | ] [ 9 ],$
- 4. The limit switches must be adjusted so to take action slightly before reaching the desired opening and closing end positions. To adjust the limit switches, refer to the installation manual of the barrier in use. ENTER DOWN

FNTFR

- 5. Perform a complete opening ( ) + ) keys) and closing ( ) + () cycle and check that the automation performs the corresponding operation and stops after activating each limit switch (learning operation M )
- 6. Connect the safety devices after removing the jumpers 1-6, 1-8 and 1-9, or reactivating the corresponding inputs using the menu parameters  $|AP| \rightarrow |B|$ ,  $|AP| \rightarrow |B|$  and |AP|Make sure the various safety devices are operating correctly.

## 10. Frequently used menu sequences

#### 10.1 Enabling the configurations

Step-by-step mode without automatic closure (residential use)

Step-by-step mode with automatic closure 1 min (residential use) [standard settings]



Opening mode with automatic closure 1 min (condominium use)



#### 10.2 Adding remote controls



#### 10.3 Configuring the NC contact safety devices

Example 1 - Configuring the photocells connected to terminals 1-8 and 1-6 [standard settings] Set



Example 2 - Configuring the safety edge with safety test simultaneously connected to terminals 1-6 and 1-8 Set



#### 10.4 Configuring the resistive safety edges

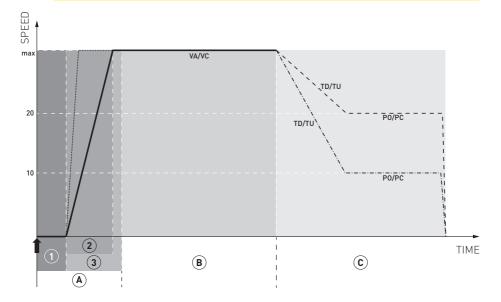
Example 1 - Configuring the resistive safety edges connected to terminals 1-6R and 1-8R Set  $\,$ 



#### 10.5 Synthetic diagram of operation



WARNING: the parameters shown in the figure must be adjusted to comply with exerted forces as outlined in EN 12453.





- Pre-flashing time: parameters WO (opening) and WC (closure)
- Acceleration time: acceleration time adjustment TA (opening) and TQ (closure)
- Start time (without detecting obstacles): fixed at 3 s (opening and closure)
- **FULL SPEED PHASE**
- Opening and closing speed: parameters VA (opening) and VC (closure).
- Opening and closing thrust: parameters R1 (opening) and R2 (closure).
- Thrust time: parameter DT (opening and closure).
- Slowdown distance: parameters **OB** (opening) and **CB** (closure).
- Slowdown speed: parameters TD (opening) e TU (closure).
- Approach speed: parameter PO (opening) e PC (closure). • Opening and closing thrust: parameters R1 (opening) and R2 (closure).
- Thrust time: parameter DT (opening and closure).

## 11. Configuration and settings menu



**NOTE**: it is possible that, owing to the type of automation and control panel, certain menus are not available.

#### 11.1 Main menu

Display	Description
WZ	WZ - Quick configuration wizard Quick configuration menu
RT	AT - Automatic Configurations. The menu allows you to manage the automatic configurations of the control panel.
BC	BC - Basic Configurations.  The menu allows you to display and modify the main settings of the control panel.
ПП	BA - Basic Adjustments. The menu allows you to display and modify the main adjustments of the control panel.
ווע	NOTE: some settings require at least three operations before they are set correctly.
RO	RO - Radio Operations. The menu is used to manage the radio functions of the control panel.
5F	<b>SF - Special Functions.</b> The menu allows you to set the password and manage the special functions in the control panel (alarm management, diagnostics enabling, FW updating)
	<b>CC - Cycle Counter.</b> The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions.
EM	<b>EM - Energy Management.</b> This menu may be used to view and modify energy saving settings and adjustments (Green Mode).
AP	AP - Advanced Parameters.  The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.).
	NOTE: some settings require at least three operations before they are set correctly.

From the main menu you can access the second level menu as follows:

- use the and keys to select the required function
- press to confirm

After confirming the selection, you access the second level menu.

For each function of the main menu, there are also additional configurations that can be viewed by enabling the  $\bigcap$  function (see the following paragraph).



**NOTE**: to check if the parameters have actually been modified, quit the relative parameter and then access it again.

The modifications will take effect from the next operation.

## 11.2 Second level menu - AT (Automatic Configurations)

	Display	Description	Selections available
	IM	DM - Direction mode RT - open to the right LF - open to the left	RILF
	HØ	H0 - Predefined setting, residential use 0.  This selection loads predefined values for certain standard parameters C5 - step-by-step control/opening operation: step-by-step RM - remote control operation: step-by-step AM - AUX1 plug-in board operation: step-by-step AN - AUX2 plug-in board operation: opening SS - selection of automation status at start-up: open	a.
AT - Automatic configurations	H_1	H1 - Predefined setting, residential use 1.  This selection loads predefined values for certain standard parameters AC - enabling of automatic closure:  TC - setting of automatic closing time:  C5 - step-by-step control/opening operation:  RM - remote control operation:  AM - AUX1 plug-in board operation:  AN - AUX2 plug-in board operation:  SS - selection of automation status at start-up:  closed	:
		CO - Predefined setting, condominium use 0.  This selection loads predefined values for certain standard parameters AC - enabling of automatic closure:  TC - setting of automatic closing time:  C5 - step-by-step control/opening operation:  C6 - step-by-step control/opening operation:  C7 - step-by-step control/opening operation:  C8 - step-by-step control/opening opening  C9 - AUX1 plug-in board operation:  C9 - opening  C9 - opening  C9 - opening  C1 - opening  C1 - opening  C1 - opening  C1 - opening  C2 - opening  C3 - selection of automation status at start-up:  C1 - opening  C1 - opening  C2 - opening  C3 - opening  C4 - opening  C6 - opening  C7 - opening  C8 - selection of automation status at start-up:  C1 - opening  C2 - opening  C3 - opening  C4 - opening  C6 - opening  C7 - opening  C8 - opening  C9 - open	:
	RI	RD - Resetting to factory settings (FACTORY RESET). ENTER	
		$\ensuremath{AA}$ - Activation of additional configurable parameters for each function of the main menu.	
	AA	FIFT OZS	18 <u>9.P</u>
		After activation you can scroll through the third level menus. The third level menus are activated for 30 min.	

## 11.3 Second level menu - BC (Basic Configurations)

	Display	Description	Selections available
	R C	AC - Enabling of automatic closure OF - Disabled ON - Enabled 1-2 - Dependent on input 30-2 hR - Push-to-operate "dead man" closure (independently of setting of parameter R9) hr - Push-to-operate "dead man" closure, obliged until complete closure (independently of setting of parameter R9)	
ions		NOTE: in hr mode if the closure command is removed before reaching the closed position limit switch, the door/gate re-opens automatically.	' _
Basic configurations	25	SS - Selection of automation status at start-up. OP - Open. CL - Closed. Indicates how the control panel considers the automation at the time of switch-on, or after a POWER RESET command.	OP CL
BC - Basic co	50	SO - Enabling of reversal safety contact functioning.  ON - Enabled.  OF - Disabled.  When enabled (ON) with the automation idle, if the contact 1-8 is open, all operations are prevented.  When disabled (OF) with the automation idle, if the contact 1-8 is open, opening operations are permitted.	
	ΝI	NI - Enabling of NIO electronic anti-freeze system.  ON - Enabled.  OF - Disabled.  When enabled (ON), it maintains the efficiency of the motor even at low ambient temperatures.  NOTE: for correct operation, the control panel must be exposed to the same ambient temperature as the motors.	<u>OF</u>
		The intervention temperature for the NIO system can be set by selecting $HP \rightarrow TN$ .	

## 11.3.1 Additional BC level parameters that can be configured (available with $\overrightarrow{H} \overrightarrow{T} \rightarrow \overrightarrow{H} \overrightarrow{H}$ enabled)

	Display	Description	Selections available
	۵5	C5 - Operation of command associated with contact 30-5 (wakeup from stand-by) 1-3 - Opening 1-5 - Step-by-step L6 - Courtesy light command N0 - Input 5 disabled	1-31 <u>-5</u> NOLG
Basic configurations	35	35 - Operation of command associated with contact 30-3 1-3 - Opening 1-5 - Step-by-step LG - Courtesy light command NO - Input 3 disabled	1-31-5 NO L G
nfia	RM	RM - Radio receiver operation 1-3 - Opening 1-5 - Step-by-step	1-31-5
3asic co	ЯM	AM - Operation of AUX1 plug-in control board 1-3 - Opening 1-5 - Step-by-step NO - Disabled	1-31 <u>-5</u> NO
BC - E	AN	AM - Operation of AUX2 plug-in control board 1-3 - Opening 1-5 - Step-by-step NO - Disabled	1-31 <u>-5</u> NO
	PP	PP - Setting of step-by-step sequence via command 30-5 ON - Opening-Stop-Closing-Stop-Opening OF - Opening-Stop-Closing-Opening	ONOF
	55	S5 - Duration of STOP in step-by-step sequence via command 30-5 ON - Permanent (automatic closure is excluded until a new command is given) OF - Temporary (the automatic closure timer intervenes, if enabled)	ON OF

## 11.4 Second level menu - BA (Basic Adjustment)

11.	Display	Description	Selections available
	MT	MT - Display of type of automation. 20 - Motor with 2000 kg capacity (CROSS20VEI). 35 - Motor with 3500 kg capacity (CROSS35VEI). NOTE: this parameter is DISPLAY only.	2035
	TC	TC - Setting of automatic closing time. [s] It is set with different intervals of sensitivity from 0s to 59s in 1-second steps - from 1 min to 2 min in 10-second steps.	0059 11,21 100
	RP	RP - Adjustment of partial opening measurement. [%] Adjusts the percentage of operation in relation to the total opening of the automation. 10 - Minimum. 99 - Maximum.	10,99
nent	TP	TP - Setting of automatic closing time after partial opening. [s] It is set with different intervals of sensitivity from 0s to 59s in 1-second steps - from 1 min to 2 min in 10-second steps.	00/59 11,21
Basic adjustment	V A	VA - Opening speed. [cm/s] CROSS20VEI 10 - Minimum. 30 - Maximum. CROSS35VEI 10 - Minimum.	CROSS20VEI
BA - Ba		25 - Maximum.	10,25
	VE	VC - Closing speed. [cm/s] CROSS20VEI 10 - Minimum. 30 - Maximum. CROSS35VEI	CROSS20VEI
	V L	10 - Minimum. 25 - Maximum.	CROSS35VEI
		R1 - Adjustment of the thrust during OPENING [A] Stops the movement with disengagement and alarm [] [] if the motor current exceeds the threshold for a time greater than parameter [] [7]; the next operation will be carried out in learning mode.  CROSS20VEI	CROSS20VEI
	רז וֹ	3.5 - Minimum. 6.0 - Maximum. CROSS35VEI 4.5 - Minimum. 9.9 - Maximum.	CROSS35VEI

t	Display	Description	Selections available
Basic adjustment		R2 - Adjustment of the thrust during CLOSURE [A] Stops the movement with disengagement and alarm OE if the motor current exceeds the threshold for a time greater than parameter DT; the next operation will be carried out in learning mode. CROSS20VEI	CROSS20VEI
BA - Basic	רל כ	3.5 - Minimum. 6.0 - Maximum. CROSS35VEI 4.5 - Minimum. 9.9 - Maximum.	CROSS35VEI



**NOTE**: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

11.4.1 Additional BA level parameters that can be configured (available with  $\square$   $\square$   $\square$  analysed)

	ble w	with $oldsymbol{P} \ oldsymbol{T}  o oldsymbol{P} \ oldsymbol{P}$ enabled)	
	Display	Description	Selections available
	пт	DT - Thrust time duration. (s) Value relating to parameters R1 and R2 [s]. CROSS20VEI and CROSS35VEI 0.5 - Minimum. 5.0 - Maximum.	CROSS20VEI
ent	i II		CROSS35VEI
Basic adjustment	TA	TA - Adjustment of acceleration time during opening. [s] 0,5 - Minimum. 9,9 - Maximum.	0.5,9.9 3.0
Basic a	TQ	TQ - Adjustment of acceleration time during closing. [s] 0,5 - Minimum. 9,9 - Maximum.	Ø.5,9.9 3.0
BA -	l' 11	VM - Initial movement speed. [cm/s] 10 - Minimum. 20 - Maximum.	10/20
	T]	TD - Adjustment of deceleration time during opening. [%] Adjusts the deceleration ramp slope. 10 - Minimum. 99 - Maximum.	10.99
	ТШ	TU - Adjustment of deceleration time during closing. [%] Adjusts the slope of the deceleration ramp during closure. 10 - Minimum. 99 - Maximum.	10,99

	Display	Description	Selections available
		OB - Adjustment of slowdown distance during opening. [cm] Indicates the distance from the end of the opening stroke where the deceleration ramp begins. 05 - Minimum. 99 - Maximum.	05,99 80
ent		OB - Adjustment of slowdown distance during closing. [cm] Indicates the distance from the end of the closing stroke where the deceleration ramp begins. 05 - Minimum. 99 - Maximum.	0 5,9 9 80
Basic adjustment	P ()	PO - Adjustment of approach speed during opening. [cm/s] Indicates the speed from the end of the deceleration ramp to the end of the opening stroke.  10 - Minimum.  20 - Maximum.  NOTE: gradually increase the approach speed if there is a series of quick vibrations (chattering) in heavy gates installed with a slight incline.	10,20
BA - Basi	PC	PC - Adjustment of approach speed during closing. [cm/s] Indicates the speed from the end of the deceleration ramp to the end of the closing stroke. 10 - Minimum. 20 - Maximum.	10,20
<b>a</b>	LP	LP - LP output operating mode See tab. 11.4.1	01 01
	13	<b>13 - 13 output operating mode</b> See tab. 11.4.1	03 03



**NOTE**: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

# BA - Basic adjustments

Table 11.4.1> Operating modes of configurable outputs 13 and LP (parameters 13 and LP)

Modalities to the manoeuvring phase							
LP-13 output operating mode	Entrance closed	Open prelamp	Opening stroke	Open entrance	Closed prelamp	Closing stroke	Entrance closed Open prelamp Opening stroke Open entrance Closed prelamp Closing stroke CB* Entrance closed
<b>00</b> : Courtesy light		淨	LU**	<i>`</i> #			
<b>01</b> : ON-OFF flashing light							
02: Permanent flashing light (auto-flashing)		<i>3.2</i>	<b>*</b>			<i></i>	
03: Proportional indicator light for open gate				*	Ħ	i	
<b>04</b> : Indicator light for open gate			I	**	I		
05: Gate stationary and closed indicator light	***						<i>**</i>
<b>06</b> : Gate stationary and fully open indicator light				<i>`</i> #			
07: Gate moving indicator light		3T	<b>*</b>		ı	<i></i>	
<b>08</b> : Gate opening indicator light		2	14				
09: Gate closing indicator light					ı		
10: Red light control / proportional shaft lights	<b>*</b>				Ħ		<i>;;</i> ;
11: Red light flashing control with closed gate/door and proportional input	=	Ī					-
during the operation 12: Electromagnetic lock control - QIKAFE	<i>₩</i>						<i>₩</i>
ON: Output always active			ı	*	ı		



LP-13 special operating mode

13: STOP signalling / safety switching

14: Maintenance alarm

\* CB: Deceleration distance on closing \*\* LU: Courtesy light switch-on time

11.		na tevet mena - Ro (Radio Operations)	
	Display	Description	
	SR	SR - Remote control storage.  You can directly access the Remote control storage menu even with the display to only with the Display visualisation mode option set to 00 or 03:  - for transmitting a remote control not present in the memory; - for transmitting an unstored channel of a remote control already present ory.  ENTER  22 S  WARNING: if the display shows ND flashing, the remote control may already	in the mem-
		TX - Visualisation of counter showing remote controls stored.	
	TX	ENTER  The state of the state o	
		MU - Indication of maximum number of remote controls that can be stored in the integrated memory.	Selections available
RO - Radio operations	МЦ	You can store a maximum of 100 or 200 remote control codes.  ENTER  O 2 s  20 - 200 remote controls that can be stored.  10 - 100 remote controls that can be stored.  WARNING: selecting M → →	20 10
R0 - I	RK	RK - Menu navigation using remote control keyboard.  ON - Enabled  OF - Disabled  With the display turned off, quickly type in the sequence of keys ③ ② ②  ④ ① from the stored remote control you want to use.  Make sure all the CH keys are stored.  WARNING: during navigation with a remote control keyboard ALL the stored remote controls are inactive.  1 (Enter)  2 (Δ)  3 (Esc)  4 (∇)  To aid vision and adjustment (avoiding the need to continuously press the remote control unit), press the UP ↑ or DOWN ↓ key once to begin slowly scrolling through the parameters. This scrolling movement is faster if the UP ↑ or DOWN ↓ key is pressed twice. To stop the scrolling, press ENTER.  To confirm your choice of parameter, press ENTER again.  To test any new setting, switch off the display and issue an opening command using key ③.  Navigation using a remote control keyboard is automatically disabled after 4 minutes of inactivity or by setting R ★ → □ F.	ON OF

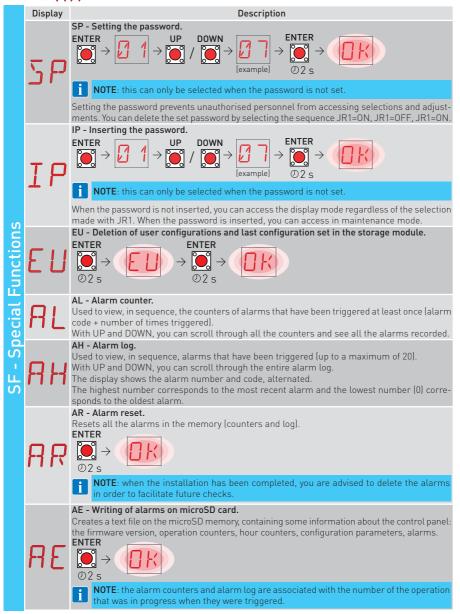
# 11.5.1 Additional configurable RO level parameters available with $\sqcap$ $\intercal$ $\rightarrow$ $\sqcap$ $\sqcap$ enabled

	Display	Description Selection: available
RO - Radio operations	E 1 E 3 E 4	C1, C2, C3, C4 - Selection of CH1, CH2, CH3, CH4 function of stored remote control.  N0 - No setting selected  1-3 - Opening command  1-4 - Closure command  1-5 - Step-by-step control  P3 - Partial opening command  LG - Courtesy light on/off command  1-9 - STOP command  If even just one [any] CH key of the remote control is stored, the opening or step-by-step command is implemented.  NOTE: the
10 - Rac	EΑ	EA - Total memory deletion.  ENTER  ENTER  O 2 S  O 2 S
Ľ	RE	RE - Setting memory opening from remote control.  OF - Disabled  ON - Enabled. When enabled (ON), the remote programming is activated.  To store new remote controls without using the control panel, refer to the remote control instructions.  NOTE: make sure you do not accidentally memorise unwanted remote controls.
	EР	EP -Setting the coded area messages  If the possibility to receive coded messages is enabled, the electronic panel will be compatible with remote controls of the "ENCRYPTED" type.
	M 5	MS - Backward compatibility setting with older generation GOL4 remote controls.  OF - Compatibility with old generation GOL4 and new ZEN remote controls.  ON - Compatibility with ZEN series remote controls  NOTE: MS=ON is recommended if only ZEN series remote controls are used on the system.

## 11.6 Second level menu - SF (Special Functions)

	Display	Description
		CU - Visualising the control panel logic and power firmware versions.
	$\Gamma II$	$\nearrow R. \rightarrow 1.1 \rightarrow .00 \rightarrow -M \rightarrow 1.6$
		Logic firmware 1.1.00
		Power firmware 1.6 SV - Saving user configuration on control panel storage module and/or on Selections
		microSD card. available
		ENTER  UP DOWN  [example]  O 2 s
tions	51	By selecting $\mathbb{R} \bigcirc \to \mathbb{M} \cup \to 1 \bigcirc \mathbb{Q}$ you can save up to 2 personalised configurations in memory positions $\cup 1$ and $\cup 2$ only with the storage module present on the control panel.  With a microSD on the control panel, up to 2 personalised configurations can be
ct		saved in positions ]] 1 and ]] 2.
i j		WARNING: if R □ → M □ → 2 ② is selected, no user configuration can be saved on □ 1 and □ 2.
Special Functions		WARNING: if the display shows ND flashing, the storage module or microSD card may not be present.
e		RC - Configuration loading. ENTER UP DOWN ENTER
- Sp	םר	
S	L.	The user configurations saved previously can be loaded - U 1 and U 2 on the storage module of the control panel, or ] 1 and ] 2 on the microSD card.
		11 ←
		RL - Loading of last configuration set.
	۵i	ENTER  O2 s  O2 s
	\ L	The control panel automatically saves the last configuration set, and keeps it memorised in the storage module or microSD card.
		In the event of a fault or the replacement of the control panel, the last configuration of the automation can be restored by inserting the storage module or microSD card and loading the configuration in question.

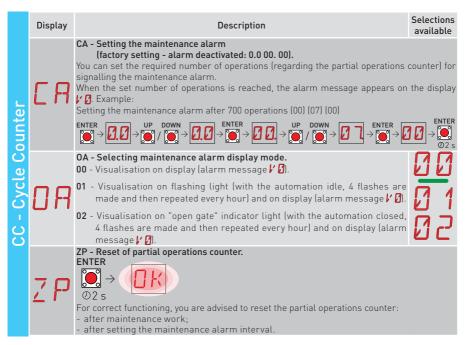
# 11.6.1 Additional configurable SF level parameters available with ☐ Ţ → ☐ ☐ enabled



#### 11.7 Second level menu - CC (Cycles Counter)

<u></u>	Display	Description
¥		CV - Display of total operations counter.
Counter	LV	ENTER  D  1  1  1  1  1  1  1  1  1  1  1  1
<u>ا</u> ه		CP - Display of partial operations counter.
- Cycle	[ } <sup>2</sup>	$ \begin{array}{c} \text{ENTER} \\ \text{O} \end{array} $ $ \begin{array}{c} \text{OPERATIONS} \\ OPERATION$
		CH - Display of power supply hour counter.
22	LH	

# 11.7.1 Additional configurable CC level parameters available with ☐ Ţ → ☐ ☐ enabled



## 11.8 Second level menu - EM (Energy Management)

Display	Description	Selections available
EM - Energy Managemen	ES - "Green Mode" (energy-saving) (disconnection of accessories connected to terminals 0-1 when the automation is in standby).  ON - Enabled (the red point on the right of the display flashes every 5 s. Outputs +LP- and 30-13 are not managed in low-consumption mode).  OF - Disabled.  Power supply disconnection mode is activated after 15 s with the gate closed, or when the gate is idle and automatic closure is not enabled.  The automation resumes normal operation when a command is received from the radio board (ZENRS-ZENPRS) or after a contact 30-5, 30-20, 30-3 or 30-4.  WARNING: if you use accessories that need to remain powered even with Green Mode enabled (e.g. LAN4 or GOPAV), set the jumper AUX1-2 relating to the slot used on power supply 0-30.	

#### 11.9 Second level menu - AP (Advanced Parameters)

	1 1./	5000	ila tevet illella. Al (Advalleea i al allieter.	رر	
		Display	Description	Selections	s available
		16	<ul> <li>D6 - Selection of device connected to terminals 1-6.</li> <li>N0 - None.</li> <li>SE - Safety edge (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection  PP → IE).</li> <li>S41 - Safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection  PP → IE).</li> <li>PH - Photocells.</li> <li>P41 - Photocells with safety test.</li> </ul>		5 E P H
	AP - Advanced Parameters	18	D8 - Selection of device connected to terminals 1-8. N0 - None. SE - Safety edge. S41 - Safety edge with safety test. PH - Photocells. P41 - Photocells with safety test.	110 124 124 124 134 134 134 134 134 134 134 134 134 13	5 E P H
	Advanced	6 R	<ul> <li>6R - Device connected to terminal 6R</li> <li>NO - None.</li> <li>01 - Stop with disengagement during both opening and closing operations. [Once the idle resistance value (8.2K) has been reset, the operation is resumed].</li> <li>02 - During closure, a significant variation in the resistance value above or below the idle resistance value (8.2 kΩ) stops and reverses the movement. When the automation is stationary, all operations are disabled.</li> </ul>	<u> </u>	02
	AP -	8 R	<ul> <li>8R - Device connected to terminal 8R</li> <li>NO - None.</li> <li>01 - Stop with disengagement during both opening and closing operations. [Once the idle resistance value (8.2K) has been reset, the operation is resumed].</li> <li>02 - During closure, a significant variation in the resistance value above or below the idle resistance value (8.2 kΩ) stops and reverses the movement. When the automation is stationary, all operations are disabled.</li> </ul>		02
		R 9	R9 - Configuration of input 30-9. N0 - Disabled. 9P - Open state of an input triggers permanent stop. 9T - The opening of the input causes a temporary stop. When the contact closes, the automatic closure time is activated (if enabled). HR - With the input open, the automation works in "hold-to-run" mode.	7	9T HR

	Display	Description	Selections available
AP - Advanced Parameters	<b>6</b> 8	68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8.  NO - None.  SE - Safety edge.  S41 - Safety edge with safety test.  If different from NO, the simultaneous opening of inputs 1-6 and 1-8 causes:  - movement stop and reversal during a closing operation.  - stop and disengagement of a duration depending on the selection   □ → □ € during an opening operation.	241 2541
	115	<ul> <li>DS - Setting of display visualisation mode.</li> <li>00 - No information displayed.</li> <li>01 - Commands and safety devices with radio test [see paragraph 9.2]. Display of countdown to automatic closing time.</li> <li>02 - Automation status [see paragraph 13.1].</li> <li>03 - Commands and safety devices [see paragraph 13.2].</li> <li>NOTE: the setting  allows you to see when a radio transmission is received, for range checks.</li> </ul>	נאנאנאנא נא גייטטט

ations to allow the control panel to be set correctly and detect any friction during operations.

NOTE: make adjustments gradually and only after performing at least three complete oper-

# 11.9.1 Additional AP level parameters that can be configured (available with $\sqcap$ $\intercal$ $\rightarrow$ $\sqcap$ $\sqcap$ enabled)

	Display	Description	Selections available
AP - Advanced Parameters	LШ	LU - Setting the courtesy light switch-on time (s).  To enable this parameter, set at least one of the selections L P → 00 or 1 → 00 as a courtesy light.  It is set with different intervals of sensitivity.  NO - Disabled.  from 1s to 59s in 1-second steps from 1 min to 2 min in 10-second steps from 2 min to 3 min in 1-minute steps  ON - Permanently enabled (switched off via remote control).  NOTE: the courtesy light switches on at the start of each operation	NO 159 1',2' 2', <u>3'</u> 0N
	L G	LG - Switch-on time for independently commanded courtesy light. [s] To enable this parameter, set at least one of the selections  ○ P → ② ○ or 1 → ② ○ as a courtesy light. It is set with different intervals of sensitivity. NO - Disabled from 1s to 59s in 1-second steps from 1 min to 2 min in 10-second steps from 2 min to 3 min in 1-minute steps ON - Switched on and off with remote control.  NOTE: the switching on of the light does not depend on the start of an operation, but can be commanded separately using the special remote control key.	NO 159 1' • 2' 2' • <u>3'</u>
	PA	PA - Automation parallel (see examples of applications) Sets the type of automation parallel 01 - Simultaneous automations 02 - Interlocked automations with one-way or two-way transit, without presence detection 03 - Interlocked automations with one-way transit, with presence detection	1,1 -1

	Displa	TN - Setting of intervention temperature for NIO electronic anti-freeze system and automatic HS ramps [°C]	Selections	5	able
		NOTE: With T T parameter the highest/lowest temperature reached by the control unit can be checked.		0	
	115	HS - Automatic ramp adjustment.  ON - Enabled.  OF - Disabled.		N	
	ri <u> </u>	When enabled (ON), at low ambient temperatures the acceleration time T diminishes to the minimum value.  NOTE: for correct operation, the control panel must be exposed		F	
	T }	TB - Permanent display of the internal control panel temperature. [°C]			F
meters	N E	WO - Setting of pre-flashing time during opening. [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the opening operation from a voluntary command. 00 - Minimum 05 - Maximum		00	5
AP - Advanced Parameters	11[	<ul> <li>WC - Setting of pre-flashing time on closing. [s]</li> <li>Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the closing operation from a voluntary command.</li> <li>00 - Minimum</li> <li>05 - Maximum</li> </ul>		0	5
- Advan	T 2	TS - Setting of renewal of automatic closing time after safety device release. [%] 00 - Minimum 99 - Maximum		9	9
AP.	l' F	VR - Setting of learning speed. [cm/s] 10 - Minimum 20 - Maximum	10		
	ΗF	HF - Heavy Traffic function When activated, this function automatically sets the automatic reclosure time to 190 s.  00 - Not activated 01 - Reduces motor overheating: it is activated if, in the last 10 minutes, the motor is in operation for:  • > 3 minutes for CROSS20VEI  • > 5 minutes for CROSS35VEI.  It is deactivated when the motor is in operation for less than:  • 2' 30" for CROSS35VEI.  02 - Reduces the mechanical stress caused by reversal: it is activated when the number of reversals without touching the closed limit switch is > 3; it is deactivated when the automation touches the closed limit switch.  03 - Applies criterion 01 or criterion 02.	02 00		1 3

### 12. Diagnostics

#### 12.1 Data Logging integrated in the card

The Ditec LCU43A / LCU43B control panel is equipped with an internal system which allows the installer to check whether any alarms have been triggered, see how many times each alarm has been triggered, and view a log of the last twenty alarms.

#### 12.1.1 Alarm counter

With the third level menus enabled ( $\mathsf{FT} \to \mathsf{FH}$ ), go to  $\mathsf{SF} \to \mathsf{FL}$  to see all the alarms recorded by the electronic panel. The display alternately shows the alarm code and the number of times it was triggered.

Example: M0 \_ 05 \_ M0 \_ 05 \_ ....

UP DOWN

Use the and keys to scroll through the entire list of alarm counters.

#### 12.1.2 Alarm log

With the third level menus enabled  $(AT \rightarrow AA)$ , go to  $SF \rightarrow AA$  to see the alarm log (the last 20 alarms recorded). The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number corresponds to the oldest alarm.

Example: - 1 \_ M0 \_ - 1 \_ M0 \_ ....

Use and to scroll through the alarm log.

#### 12.1.3 Exporting information on the microSD

With the third level menus enabled  $[HT \to HH]$ , the microSD card inserted and the automation stationary, go to  $SF \to HE$  to export all the electronic panel parameters on the microSD. The LCU43A e LCU43B\_INFO.txt text file created on the microSD contains all the alarm counters, a log showing the last twenty alarms, the operating statistics and the complete configuration of the electronic panel.

By inserting the microSD in a PC and opening the file LCU43A\_INFO\_.txt with the Ditec software, you can view all the electronic panel data.



**NOTE**: when the installation is complete, you are advised to delete the internal data logging.

#### 12.2 Extended data logging on microSD

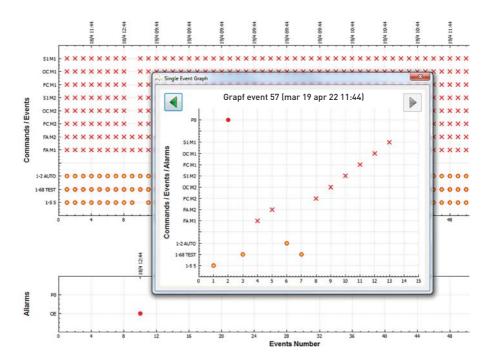
The Ditec LCU43A / LCU43B control panel can record every event and/or alarm for every operation performed.

This is made possible by leaving a microSD inserted in the relative connector and then, with the third level menus enabled  $(AT \rightarrow AA)$ , setting  $(AT \rightarrow AA)$ , setting  $(AT \rightarrow AA)$ .

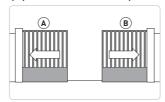
In this way, at the end of every operation the electronic panel will save all the events recorded up to that moment on the microSD (in the LCU43A / LCU43B .log file in the LCU43A\_LOG / LCU43B\_LOG folder)

The recorded logs can be viewed by inserting the microSD in a PC and opening the LCU43A / LCU43B .log file using the Amigo Ditec software.

This is an example of the visualisation of recorded events:



## 13. Examples of application for parallel automations



The parallel connection synchronises opening, closure and reopening following an obstacle during closure, and the activation of the flashing lights.

For an obstacle during opening, the safety devices (safety edges) are each installed on the relative wing and they act independently.

Define which automation is the MASTER and which is the SLAVE.

The MASTER automation may be the one chosen to be only partially opened (1-20 connected).

- 1. Disconnect connectors 1-G1-G3 from the control panels.
- 2. Set the following parameters on both automations via the display:

Setting advanced parameters



Setting input mode AP > 5 1 > 5 Y

Set automation parallel mode RP > PR > 0 1

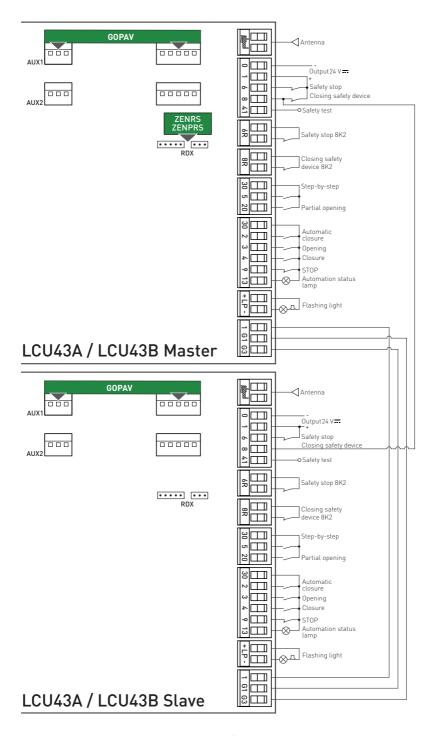
Set **BC** > **50** > **0F**.



**NOTE**: if SD > DN, command 1-8 will trigger the stoppage of the wing movement if one wing is closed and the other is closing (without reopening the closed wing).

#### Do NOT alter the setting of parameter HP > 5M > 00.

- 3. Reconnect connectors 1-G1-G3.
- 4. Enable automatic closure on the MASTER automation only, with BC > HC > DN. or with BC > HC > I 2 (if you want to use a timer).
- 5. Set the required automatic closing time ( ) on the MASTER automation (high enough to allow the SLAVE automation to open completely). With these settings, the automations will make simultaneous closing operations at the end of the time set by the MASTER automation TC.
- 6. Install a single GOLR GOL868R radio receiver on the MASTER automation.



#### 13.1 Examples of application for interlocked automations with one-way or two-way transit, without presence detection

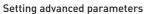
With these settings, command 1-3 launches an opening operation on the automation it is connected to, with closure after the time set with BA > TC.

Once the delay time set with RP > TO has elapsed, the other automation will open. It will close after the time set with **3** A > T C.

Commands 1-5, 1-4 and 1-20 can be used in special cases, for instance to allow very long vehicles to pass through.

Command 1-9 can be used to interrupt the interlocking sequence - i.e. annul the command given to automation B.

- 1. Disconnect connectors 1-G1-G3 from the control panels.
- 2. Set the following parameters on both automations via the display:



AT>AA 33>

Setting input mode AP>61>5Y Set automation parallel mode AP > PA > 02

- 3. Reconnect connectors 1-G1-G3.
- 4. Set **3** C > **RM** > **1-3** on both automations.

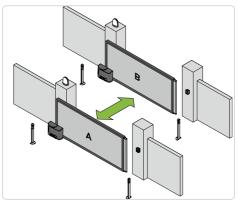


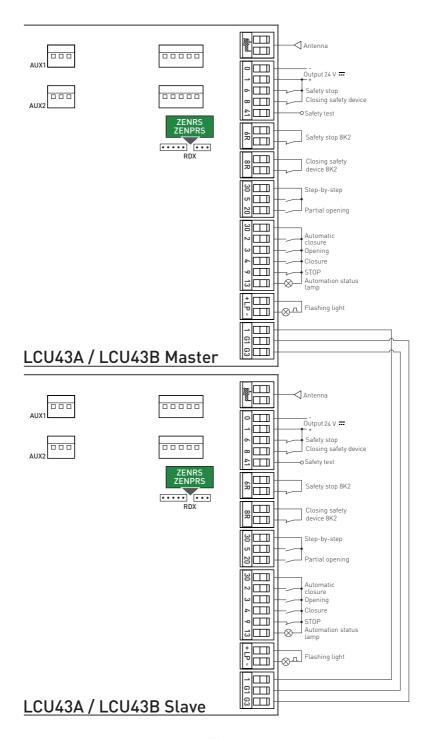
NOTE: you are advised to store two different keys of the transmitter rather than just one (e.g.: key 1 to open automation A and key 2 to open automation B).

- 5. If required, enable automatic closure  $\mathbb{B} \mathcal{L} > \mathbb{H} \mathcal{L} > \mathbb{O} \mathbb{N}$  on both automations.
- 6. Set the required automatic closure time ( A > T ) on both automations.
- 7. Set the delay time  $\mathbb{AP} > \mathbb{TO}$  (from 0 to 30s) on both automations.
- 8. The booking function BC > PG > DN can be enabled on both automations if a vehicle arrives from the same direction while another one is still in transit. A second opening command is stored and executed as soon as the cycle in progress terminates.



NOTE: it is advisable to use booking with one-way transit only, or at least with limited traffic in the case of two-way transit.





#### 13.2 Examples of application for interlocked automations with one-way transit, with presence detection

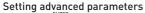
With these settings, command 1-3 launches an opening operation on the MASTER automation, with closure after the time set with **3** H > T **C** but only once the vehicle has activated the detection device installed between the two automations (e.g. a magnetic loop).

Once the delay time set with AP > T has elapsed, the SLAVE automation will open. It will close after the time set with  $\mathbf{IR} > \mathbf{IC}$ .

Commands 1-5, 1-4 and 1-20 can be used in special cases, for instance to allow very long vehicles to pass through.

Command 1-9 can be used to interrupt the interlocking sequence - i.e. annul the command given to the SLAVE automation.

- Disconnect connectors 1-G1-G3 from the control panels.
- 2. Set the following parameters on both automations via the display:



AT>AA 🔟→

Setting input mode

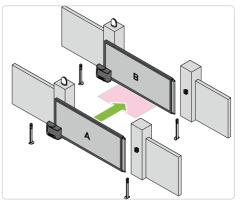
AP > 6 1 > 5 Y

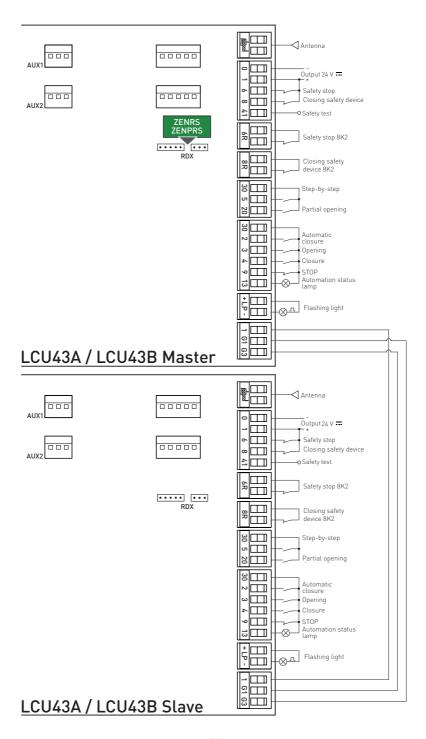
Set automation parallel mode

AP>PA>03

With this setting, the SLAVE automation does not close as long as contact 1-2 of the MASTER automation is active.

- 3. Reconnect connectors 1-G1-G3.
- 4. Set BC > RM > 1-3 on the MASTER automation.
- 5. Enable automatic closure on the MASTER automation with BC > HC > I C, and on the SLAVE automation with **3** C > A C > ON.
- 6. Set the required automatic closure time ( R > T C) on both automations.
- 7. It is advisable (but not compulsory) to install a single GOLR GOL868R radio receiver on the MASTER automation.
- 8. Set the delay time  $\mathbb{HP} > \mathbb{TO}$  (from 0 to 30s) on the MASTER automation.
- 9. The booking function BC > PG > ON can be enabled on the MASTER automation if a vehicle arrives from the same direction while another one is still in transit. A second opening command is stored and executed as soon as the cycle in progress terminates.





## 14. Signals visualised on the display

- NOTE: it is possible that, owing to the type of automation and control panel, certain visualisations are not available.
- 14.1 Display of automation status
- NOTE: the automation status display mode is only visible with Display visualisation mode set to 02.

#### AP > 115 > 02

00 1 7 5 1 7 4

Display	Description
	]M≥RT
	Automation closed.
	Automation closed. Release door open.
1	Automation open.
. 1	Automation open. Release door open.
	Automation stopped in intermediate position.
J.	Automation stopped in intermediate position. Release door open.
1 1	Automation closing.
1	Automation that slows down during closing.
00	Automation opening.
V	Automation that slows down during opening.

Display	Description
	IMPLF
	Automation closed.
	Automation closed. Release door open.
	Automation open.
	Automation open. Release door open.
	Automation stopped in intermediate position.
].	Automation stopped in intermediate position. Release door open.
1 1	Automation closing.
· ·	Automation that slows down during closing.
1 1	Automation opening.
1	Automation that slows down during opening.

#### 14.2 Display of safety devices and commands

NOTE: the safety device and command display mode is only visible with Display visualisation mode set at 01 or 03.

ברת או			
Display	Description	Display	
ו- כ	2 - Automatic closure enable command.	1-6	<b>1-6</b> - Safety device with stop during opening and closing.
I- 3 1-	<b>3</b> - Opening command.	I- B	<b>1-8</b> - Safety device with reversal during closing operation.
- L   1-	4 - Closure command.	1-9	<b>1-9</b> - STOP command.
I-5 1-	<b>5</b> - Step-by-step control.	88	68 - Simultaneous opening of contacts 6-8 (only with AP > 68 = SE or S41)

X - This card sees the other one in a RESET condition (XX)

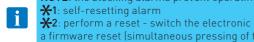
12 - The other card cannot be detected (no messages arriving on G1)



**WARNING**: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

_				
Type of alarm	Display	Description	Operation	Type of alarm
	М 3	M3 - Automation blocked or opening / closing limit switch not disen- gaged within 3 s	Check the mechanical parts	Non-blocking if it occurs less than 3 times in a row (see M9)
	MY	M4 - Motor short circuit.	Check connection of motor.	
	M	M6 - Brake absent or circuit open. Non-fatal alarm.  WARNING: CROSS20VEI only	Check the brake connection.	
	M7	<ul><li>M7 - Short circuit or brake overload. Fatal alarm.</li><li>WARNING: CROSS20VEI only</li></ul>	Check the brake connection.	Blocking - <b>★2</b>
	M9	M9 - More than 2 consecutive M3 alarms	Check the mechanical parts	<del>X</del> 2
Mechanical alarm	ΜI	MI - Current threshold exceeded 3 consecutive times.	nent obstacles along the stroke of the automation.	Blocking
chanic	MF	MF - Incorrect limit switch operation	Check the limit switch connections.	
Σ Θ	ML	ML - Limit switches inverted	Check the connection or swap the limit switches over.	
	IIM	MD - Irregular operation of motor opening limit switch.	Check connection of the motor opening limit switch.	Blocking
	ME	ME - Irregular operation of motor closure limit switch.	Check connection of the motor closing limit switch.	Blocking
		<b>OD</b> - motor overcurrent during OPENING	Check the mechanical parts and that they move freely	
	$\Box E$	<b>OE</b> - motor overcurrent during CLOSURE	Check the mechanical parts and that they move freely	
	$\square F$	<b>OF</b> - motor overcurrent with boost active during OPENING	Check the mechanical parts and that they move freely	
	06	<b>OG</b> - motor overcurrent with boost active during CLOSURE	Check the mechanical parts and that they move freely	
Alarm Settings	56	<b>S6</b> - Incorrect setting of safety device test.	Check the configuration of parameters $16,18,68$ . If $68 \rightarrow 541$ , $16$ and $18$ cannot be $941$ or $541$ .	
ılarm	l' []	<b>V0</b> - Maintenance request.	Proceed with the scheduled maintenance intervention.	
Service alarm	l'H	VH - motor thermal protection switch alarm	Check the connection and condition of the motor thermal protection switch. In the event of an alarm due to high engine speed, wait for the engine to cool down.	Blocking - <b>¥2</b>
Internal control panel alarm	I 5	15 - No voltage 0-1 (voltage regulator faulty or short circuit on accessories).	Check there is no short circuit in con- nection 0-1 and that the sum of the currents delivered to the accessories does not exceed the limit indicated in the electrical data. If the problem persists, replace the control panel.	Blocking

Type of alarm	Display	Description	Operation	Type of alarm
arm	RØ		To save the system configurations on the storage module, delete any stored remote controls and bring the total to less than 100. Set RD → MU→ 10.	
Radio operations alarm	R 3	R3 - Storage module not detected.	Insert a storage module.	
io oper	RH	R4 - Storage module not compatible with the control panel.	Insert a compatible storage module.	
Rad	R5	R5 - No serial communication with the storage module.	Replace the storage module.	
	R E	R6 - Specific storage module for testing installed.		
supply	P 1	P1 - Insufficient microswitch voltage.	Check the control panel is powered correctly.	
Power supply alarm	ΙT	IT - Short drop in power supply or power failure.	If the alarm occurs several times, check the electrical connections and power supply.	
		6 failed.	Check the device SOFA1-A2 is working correctly.	
	HU		If the supplementary SOF card is not inserted, check the safety test is disabled.	
	R 1	A1 - Test of safety sensor connected simultaneously to contacts 6 and 8 failed.	Check the wiring and correct operation of the safety sensor.	
ε		A3 - Test of safety sensor on contact 8 failed.	Check the device SOFA1-A2 is working correctly.	
Accessories alarm	ב דו		If the supplementary SOF card is not inserted, check the safety test is disabled.	
cessor	85	A5 - Test of safety sensor on contact 6 failed.	Check the edge is working properly.	
Ă	85	A6 - Test of safety sensor on contact 8 failed.	Check the edge is working properly.	
	RT	A7 - Incorrect connection of contact 9 to terminal 41.	Check that terminal 1 and 9 are correctly connected.	
	R9	A9 - Overload on output +LP	Check the device connected to output +LP- is working properly.	
	RJ	AB - Overload on output 30-13.	Check the device connected to output 30-13 is working properly.	



NOTE: the blocking alarms prevent operating of the automation system.

★1: self-resetting alarm

★2: perform a reset - switch the electronic control panel off and on again or perform a firmware reset (simultaneous pressing of the UP + DOWN). buttons)

## 15. Troubleshooting

Problem	Possible cause	Alarm signal-		Operation
The electronic panel does not switch on.	No power supply.			Check the power supply cable and the relative wiring.
	Overload on output 0-30.			Disconnect any loads connected to terminal 30.
The automation does not open or close.				Check power supply cable.
	Short circuited accessories.	I5		Disconnect all accessories from terminals 0-30 (a voltage of 24 V= must be present), then reconnect them one at a time. Contact Technical Service
	Safety contacts are open.	1-6 68	1-8	Check that the safety contacts are closed correctly (NC).
	Safety contacts not correctly connected or self-controlled safety edge not functioning correctly.	A0 A1 A3	1-6 1-8 6-8	Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge.
	Photocells activated.	1-6	1-8	Check that the photocells are clean and operating correctly.
	The automatic closure does not work.			Issue any command. If the problem persists, contact Technical Service
The automation opens/closes briefly and then stops.	There is a presence of friction.	MI OI OE	MI OF OG	Manually check that the automation moves freely and check the R 1/R2 adjustment. Check that the limit switches, if installed, are working correctly Contact Technical Service
	Incorrect connections between the photocells and the control panel.			Check that I-6 /I-8 is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board.
				Check the $\begin{picture}(20,0) \put(0,0){\line(1,0){10}} \put(0,0){\line(1,0){1$
	The radio transmission is im-			Install the aerial outside.
and does not work with the automation moving.	peded by metal structures and reinforced concrete walls.			Replace the transmitter batteries.
The remote control does not work	No storage module or incorrect storage module.	RØ R3 R5		Switch the automation off and plug in the correct storage module.
				Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module.

P2336EN

#### 16 Maintenance

The control panel doesn't require any special maintenance.

Make regular checks to ensure the seals on the box and the electrical connections are in good condition

All the rights concerning this material are the exclusive property of ASSA ABLOY Entrance Systems AB. Although the contents of this publication have been drawn up with the greatest care, ASSA ABLOY Entrance Systems AB cannot be held responsible in any way for any damage caused by mistakes or omissions in this publication. We reserve the right to make changes without prior notice.

Copying, scanning or changing in any way is expressly forbidden unless authorised in writing by ASSA ABLOY Entrance Systems AB.

The crossed-out wheelie bin symbol indicates that the product should be disposed of separately from normal household waste. The product should be recycled in accordance with local environmental regulations for waste disposal. By separating a product marked with this symbol from household waste, you will help reduce the volume of waste sent to incinerators or land-fill and minimise any potential negative impact on human health and the environment.

