

IS117 Rev.07 22/06/2016

B70/1DC

centrale di comando per cancelli scorrevoli

Istruzioni originali



IT - Istruzioni ed avvertenze per l'installatore - pag. 12

EN - Instructions and warnings for the installer - pag. 38

DE - Anweisungen und Hinweise für den Installateur - S. 64

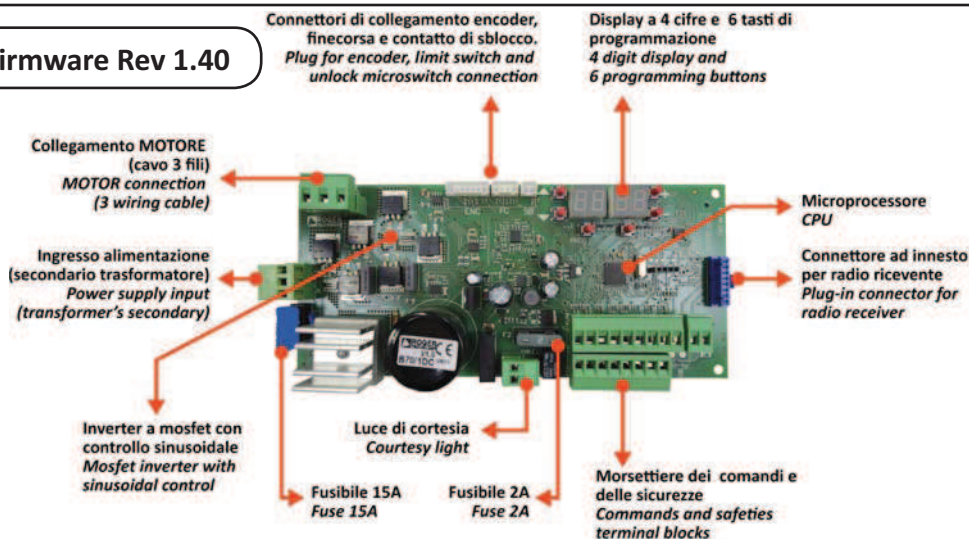
FR - Instructions et consignes pour l'installateur - p. 90

ES - Instrucciones y advertencias para el instalador - pág. 116

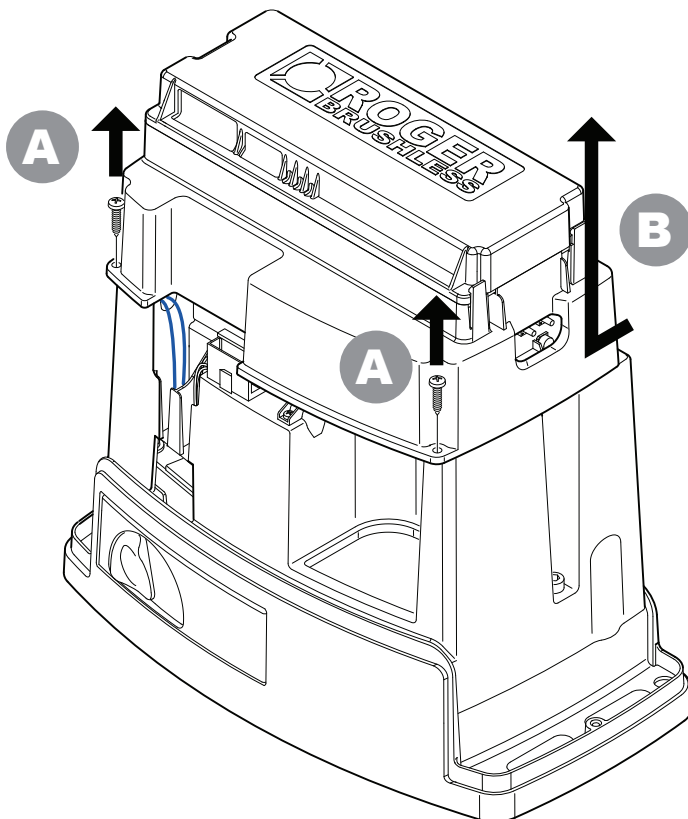
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Firmware Rev 1.40

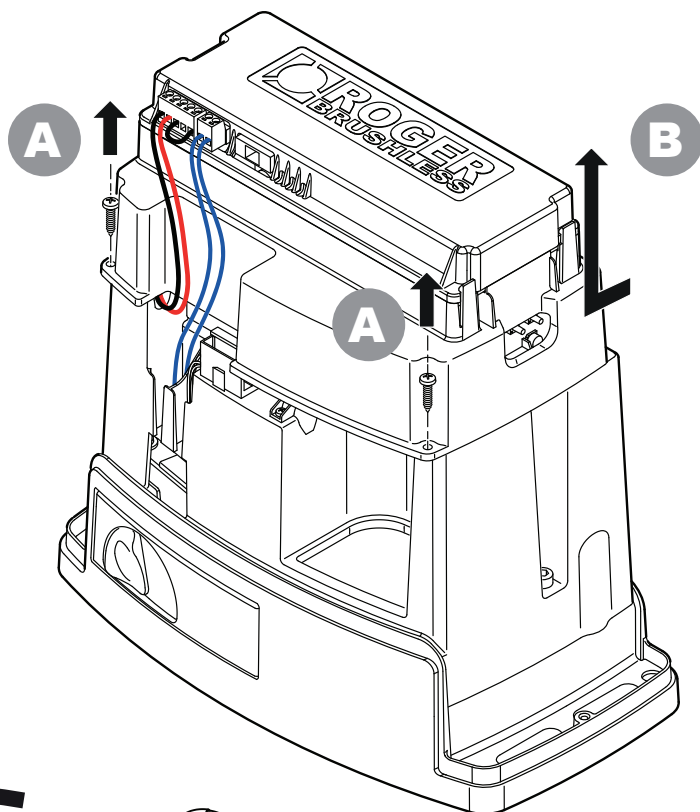


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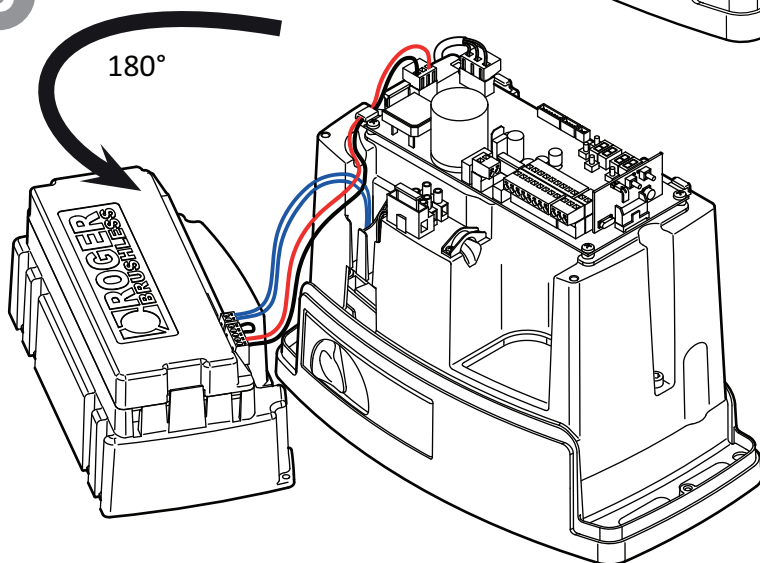


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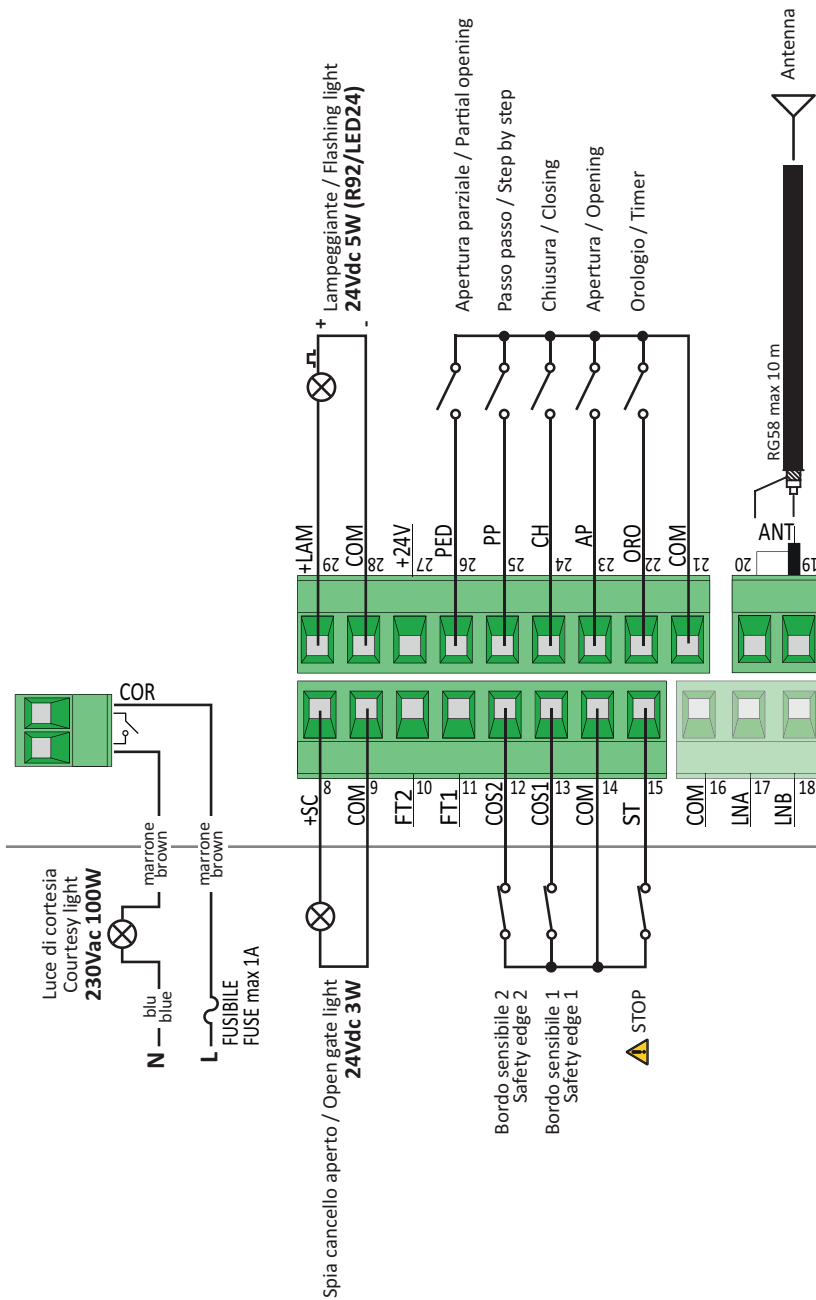
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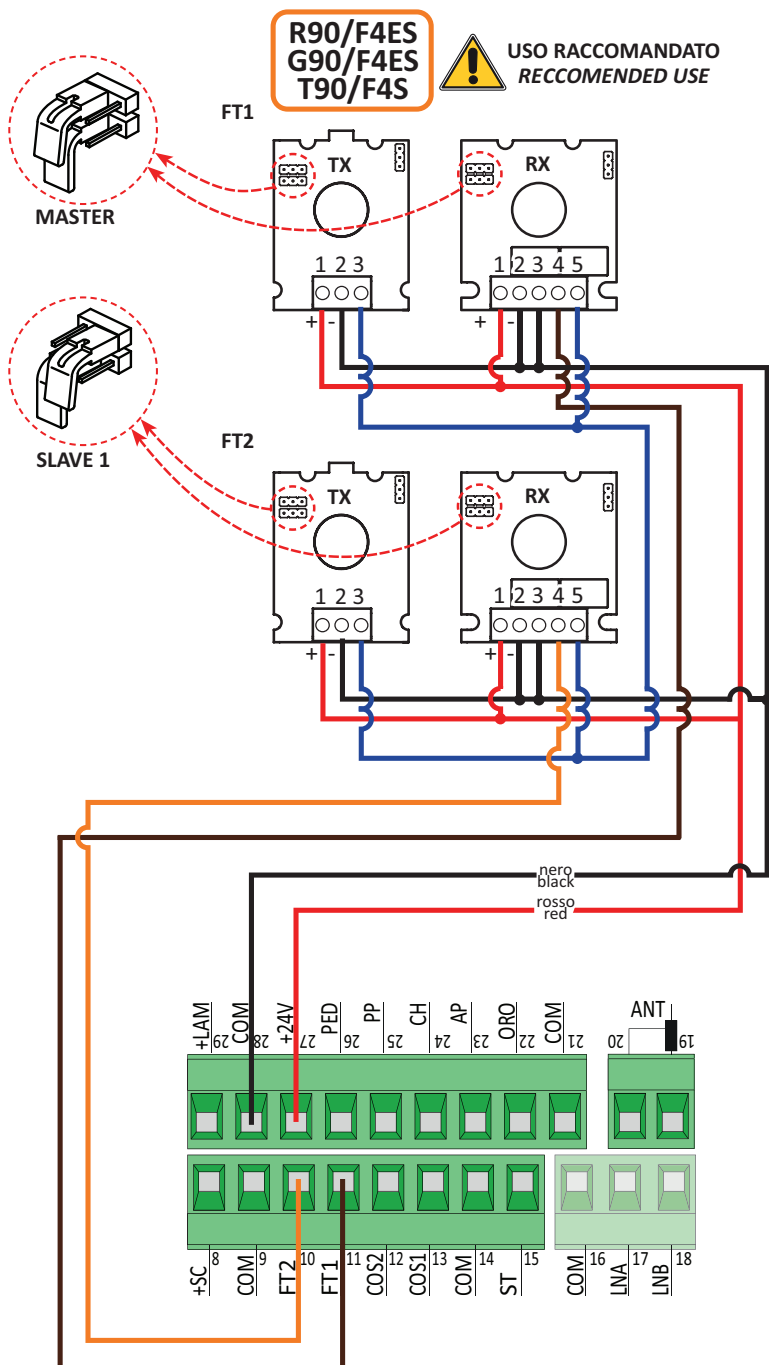


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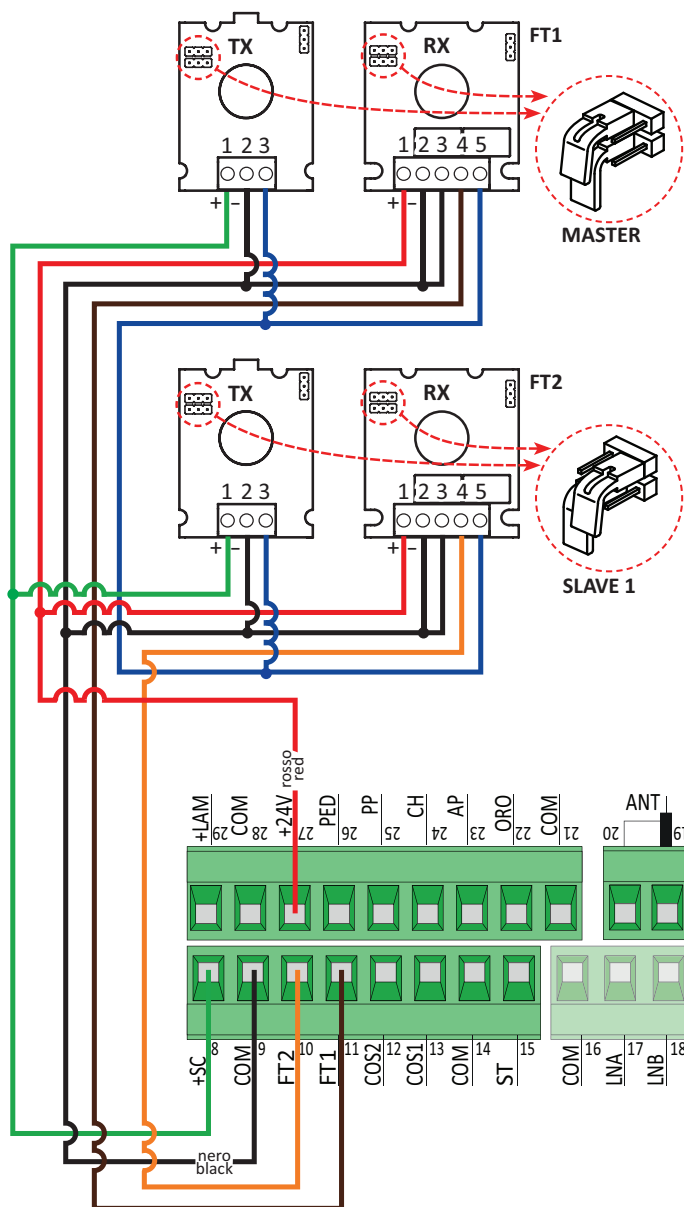




R90/F4ES
G90/F4ES
T90/F4S



USO RACCOMANDATO
RECOMMENDED USE

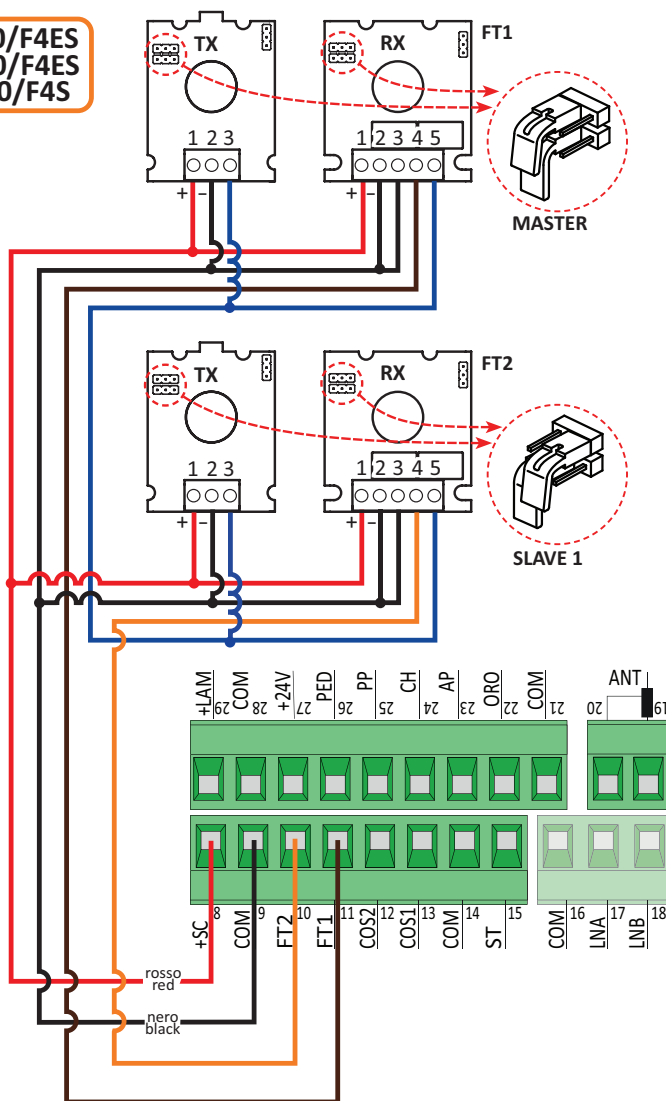


BATTERY SAVING + TEST FOTOCELLULE • PHOTOCELLS TEST
(impostare • set *AB 04*)

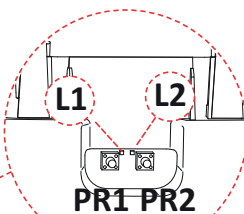
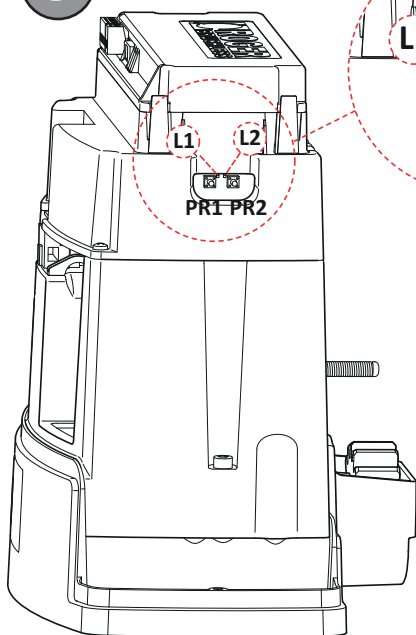
BATTERY SAVING + TEST FOTOCELLULE • PHOTOCELLS TEST
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R90/F4ES
G90/F4ES
T90/F4S

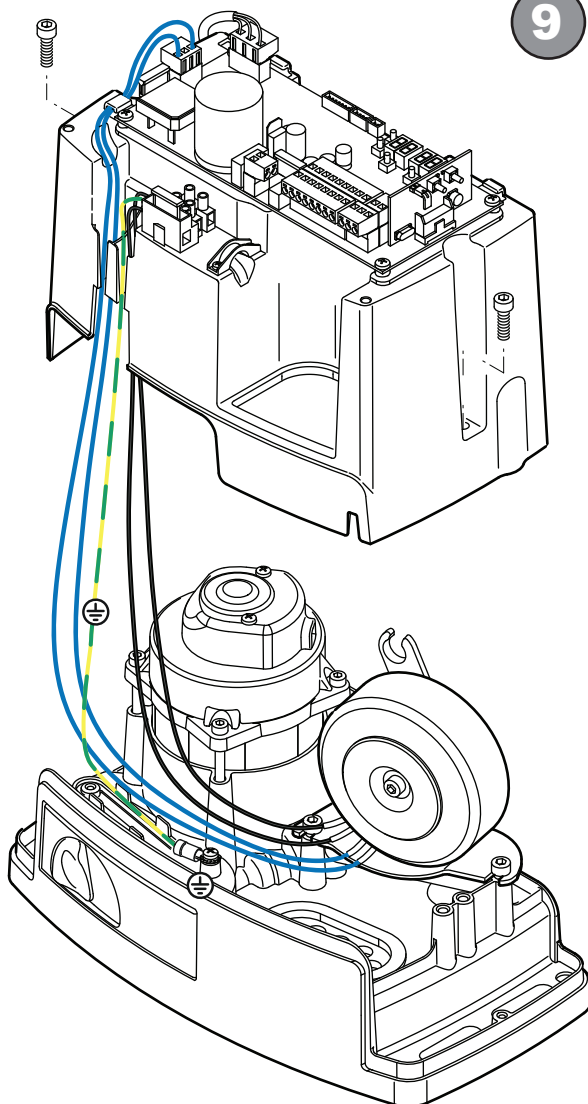


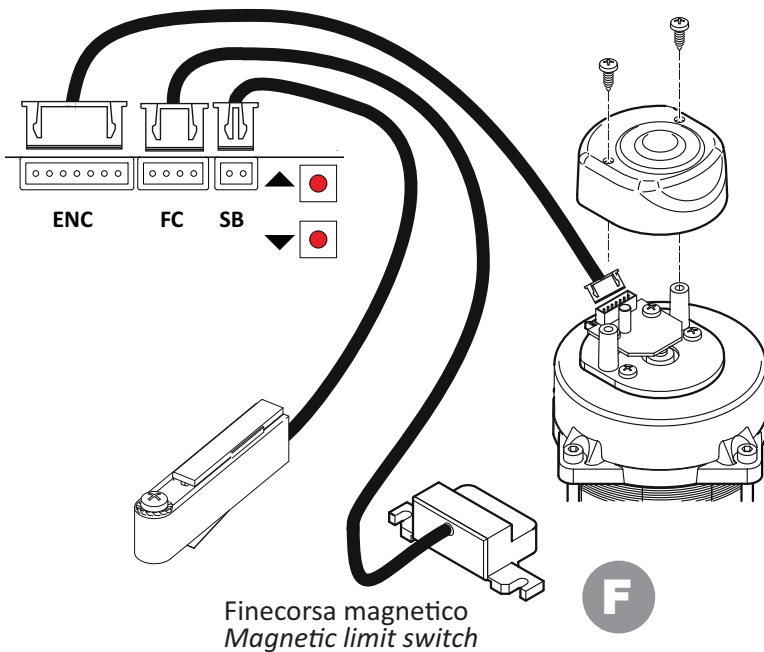
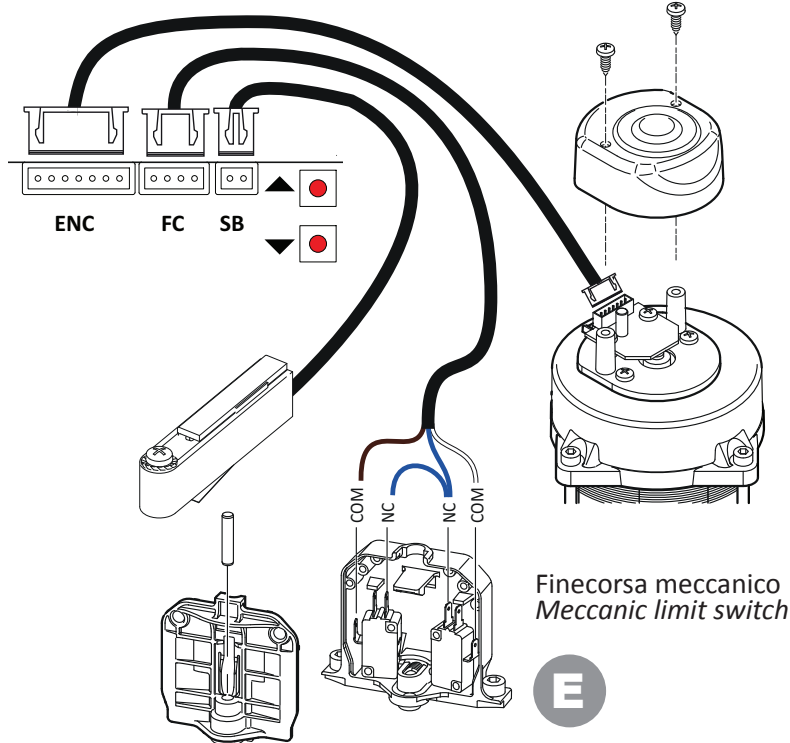
8



Canali radio
Radio channels

9





1 General safety precautions



Warning: incorrect installation may cause severe damage or injury.

Read the instructions carefully before installing the product.

This installation manual is intended for qualified personnel only.

ROGER TECHNOLOGY cannot be held responsible for any damage or injury due to improper use or any use other than the intended usage indicated in this manual.

Installation, electrical connections and adjustments must be performed by qualified personnel, in accordance with best practices and in compliance with applicable regulations.



Before installing the product, make sure it is in perfect condition.

A switch or an omnipolar cut-off switch with a contact opening of at least 3 mm must be installed on the mains power line.

Ensure that an adequate residual current circuit breaker and a suitable overcurrent cut-out are installed ahead of the electrical installation in accordance with best practices and in compliance with applicable legislation.

The European standards EN 12453 and EN 12455 define the minimum safety requirements for the operation of automatic doors and gates. In particular, these standards require the use of force limiting and safety devices (sensing ground plates, photocell barriers, operator detection function etc.) intended to detect persons or objects in the operating area and prevent collisions in all circumstances.

Where the safety of the installation is based on an impact force limiting system, it is necessary to verify that the characteristics and performance of the automation system are compliant with the requisites of applicable standards and legislation.

The installer is required to measure impact forces and programme the control unit with appropriate speed and torque values to ensure that the door or gate remains within the limits defined by the standards EN 12453 and EN 12455.

When requested, connect the automation to an effective earthing system that complies with current safety standards.

Disconnect the mains electrical power before performing any work. Also disconnect any buffer batteries used.

Only use original spare parts when repairing or replacing products.

The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.




2 Product description

The **B70/1DC** controller is a unit for the sensed control, with a high resolution encoder, of a ROGER brushless motor for automated sliding gates.

Ensure that the parameter A1 is set correctly. If this parameter is not set correctly, the automation system may not function properly.

We recommend using only ROGER TECHNOLOGY accessories and control and safety devices. Specifically, we recommend installing **R90/F4ES**, **G90/F4ES** or **T90/F4S** series photocells.

3 Technical characteristics of product

	BH30/600	BH30/800	BH30/500/HS 
MAINS POWER VOLTAGE	230 Vac \pm 10% 50 Hz (B70/1DC/115 : 115 Vac \pm 10% 60 Hz)		
MAXIMUM MAINS POWER ABSORPTION	160 W	250 W	380 W
FUSES	F1 = 15A (ATO257) motor power circuit protection F2 = 2A (ATO257) accessories power supply protection F3 = T1A (5x20 mm) / H30/500/HS/115V : T2A		
CONNECTABLE MOTORS	1		
MOTOR POWER SUPPLY	24 Vac, with self-protected inverter		
MOTOR TYPE	sinusoidal drive brushless (ROGER BRUSHLESS)		
MOTOR CONTROL TYPE	sensored field oriented control (FOC)		
RATED MOTOR POWER	45 W	75 W	120 W
MAXIMUM MOTOR POWER	125 W	200 W	350 W
MAXIMUM POWER, FLASHING LIGHT	13 W (24 Vdc)	25 W (24 Vdc)	25 W (24 Vdc)
FLASHING LIGHT DUTY CYCLE	50%		
MAXIMUM POWER	100 W 230 Vac - 40 W 24 Vac/dc (potential free contact)		
GATE OPEN LIGHT POWER	3 W (24 Vdc)		
MAXIMUM ACCESSORY CURRENT ABSORPTION	7 W (24 Vdc)	10 W (24 Vdc)	10 W (24 Vdc)
OPERATING TEMPERATURE	 -20°C  +55°C		
PRODUCT DIMENSIONS	dimensions in mm 200x90x45 Weight: 0,244 kg		

4 Description of connections

To access the control connection terminal board, remove the motor cover as shown in figure 1:

- remove the two screws **A**;
- push the cover in from the side, then lift it up (arrow **B**).

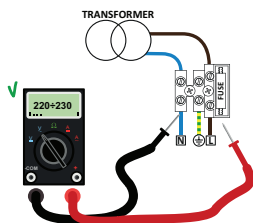
See figure 2 if the battery charger (**B71/BC**) is installed:

- remove the two screws **A**;
- push the cover in from the side, then lift it up (arrow **B**).
- turn the cover around by 180° and set it down in front of the automation system. **Warning!** Lift the cover slowly and carefully to prevent damaging the wires.

Figure 4 shows connection diagrams for connecting mains voltage to the motor control unit (**B70/1DC**).

4.1 Electrical connections

Strip the insulation from the ends of the power cable wires which will be connected to the terminal (see **D**, **fig. 3**), and secure the cable with the cable clamp.



Measure the voltage on the primary mains power connection with a tester. For the brushless automation system to function correctly, the mains power voltage must be at least 230Vac (115 Vac) \pm 10%.

If the voltage measured is not as indicated above or is unstable, the automation system may NOT work correctly.

CONNECTING CONTROL UNIT TO MAINS ELECTRICITY	L cable		
	1÷10 m	10÷20 m	20÷30 m
Power supply 230 Vac $\pm 10\%$	3x2,5 mm ²	3x2,5 mm ²	3x4 mm ²

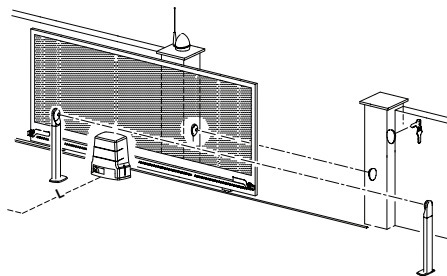
CONNECTING CONTROL PANEL TO ACCESSORIES	L cable = 1÷20 m
Photocells - Receiver	4x0,5 mm ²
Photocells - Transmitter	2x0,5 mm ²
Keypad H85/TDS - H85/TTD (connecting to control panel to decoder board)	3x0,5 mm ²
Key selector R85/60	3x1 mm ²

CONNECTING CONTROL PANEL TO FLASHING LIGHT	
Power supply 24 Vdc - LED (25 W power consumption)	2x1,5 mm ² (max 10 m)

CONNECTING CONTROL PANEL TO GATE OPEN INDICATOR	L cable 1÷20 m
Power supply 24 Vdc (3 W power consumption)	2x1 mm ²

CONNECTING CONTROL PANEL TO COURTESY LIGHT	L cable = 1÷20 m
Power supply 230 Vac (100 W power consumption)	2x1 mm ²

CONNECTING CONTROL PANEL TO ANTENNA	
Cable type RG58	max 10 m

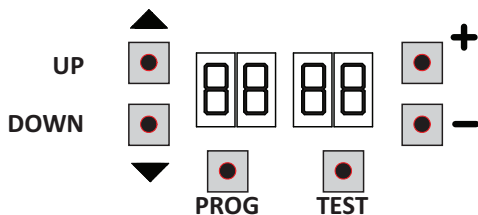


SUGGESTIONS: with existing installations, we recommend checking the cross section of the cables and that the cables themselves are in good condition.

WARNING: old cables or previous generation cables, especially if with a cross section of 3x1.5mm², may impair the performance of the digital brushless motor.

	DESCRIPTION
	<p>Mains power supply 230 Vac $\pm 10\%$ (115 Vac $\pm 10\%$) connection. Fuse 5x20 T1A. BH30/500/HS/115V: Fuse 5x20 T2A.</p>
POWER IN 	<p>Power feed input from transformer (or from B71/BC battery charger, if used). N.B.: Ready wired in factory by ROGER TECHNOLOGY.</p>
X-Y-Z 	<p>Connection to ROGER brushless motor. N.B.: Ready wired in factory by ROGER TECHNOLOGY.</p> <p>Warning! If the motor wires become disconnected from the terminal board, after reconnecting correctly, the gate travel must be acquired again as described in chapter 8.</p>

5 Function buttons and display



BUTTON	DESCRIPTION
UP ▲	Next parameter
DOWN ▼	Previous parameter
+	Increase value of parameter by 1
-	Decrease value of parameter by 1
PROG	Programme travel
TEST	Activate TEST mode

- Press the UP ▲ and/or DOWN ▼ buttons to view the parameter you intend to modify.
- Use the + and - buttons to modify the value of the parameter. The value starts to flash.
- Press and hold the + or - button to scroll quickly through values, to modify the parameter more quickly.
- To save the new value, wait a few seconds or move onto another parameter with the UP ▲ or DOWN ▼ button. The display flashes rapidly to indicate that the new value has been saved.
- Parameters can only be modified while the motor is not running. Parameters can be viewed at any time.

6 Switching on or commissioning

Power the control unit.

The firmware version of the control unit is displayed briefly.

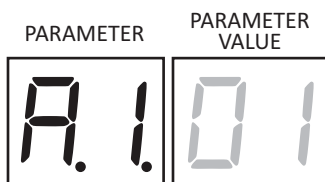
Version installed 1.40.



Immediately afterwards, the display enters the commands and safety device status mode. See chapter 7.

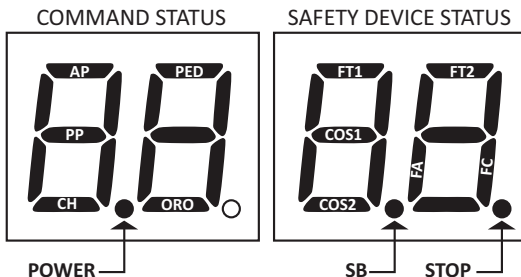
7 Display function modes

• Parameter display mode



See chapter 10 for detailed descriptions of the parameters.

- **Command and safety device status display mode**



COMMAND STATUS:

The command status indicators on the display (segments AP = open, PP = step mode, CH = close, PED = partial opening, ORO = clock) are normally off. They illuminate when a command is received (e.g.: when a step mode command is received, the segment PP illuminates).

SAFETY DEVICE STATUS:

The safety device status indicators on the display (segments FT1/FT2 = photocells, COS1/COS2 = sensing edge, FA = gate open limit switch, FC = gate closed limit switch, SB = release handle open) are normally on. If an indicator is off, the relative device is in alarm state or is not connected.

If an indicator is flashing, the relative device has been disabled with a specific parameter.

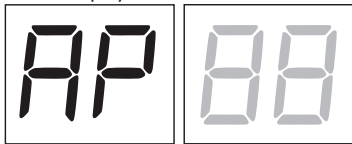
- **TEST mode**

The TEST mode is used to test activation of the commands and safety devices with visual confirmation.

To activate the mode, press the TEST button with the automatic door system at rest. If the gate is moving, pressing TEST stops the gate. Pressing the button again enables TEST mode.

If the flashing light and the gate open indicator lamp illuminate for one second each time a control is used or a safety device is activated.

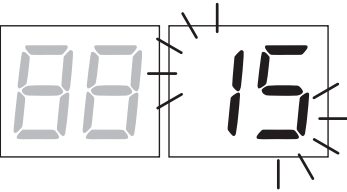
The command signal status is shown on the left hand side of the display for 5 seconds, ONLY when the respective command signal is active (AP, CH, PP, PE, OR). For example, if the gate open command is activated, the letters AP appear on the display.



The status of the safety devices/inputs is shown on the right hand side of the display. The number of the terminal relative to the safety device in alarm state flashes.

When the gate is completely open or completely closed, FA or FC is shown on the display to indicate that the gate has reached the gate open limit switch FA or gate closed limit switch FC.

Example: STOP contact in alarm state



00	No safety device in alarm state, and no limit switch activated
5b (Sb)	Release handle or lock open.
15	STOP.
13	Sensing edge COS1.
12	Sensing edge COS2.
11	Photocell FT1.
10	Photocell FT2.
FE	Both limit switches
FA	Gate open limit switch
FC	Gate closed limit switch

NOTA: If one or more contacts are open, the gate will not open or close. This does not apply for the limit switch signal state, however, which is shown on the display but does not prevent normal operation of the gate.

If more than one safety device is in alarm state, once the problem relative to the first device is resolved, the alarm for the next device is displayed. Any further alarm states are also displayed with the same logic.

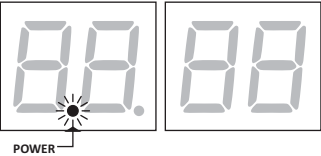
Press the TEST button again to exit test mode.

After 10 seconds with no user input, the display returns to command and safety device state display mode.

• **Standby mode**

This mode is activated after 30 minutes with no user input. The POWER LED flashes slowly.

Press UP ▲, DOWN ▼, +, - to reactivate the control unit.



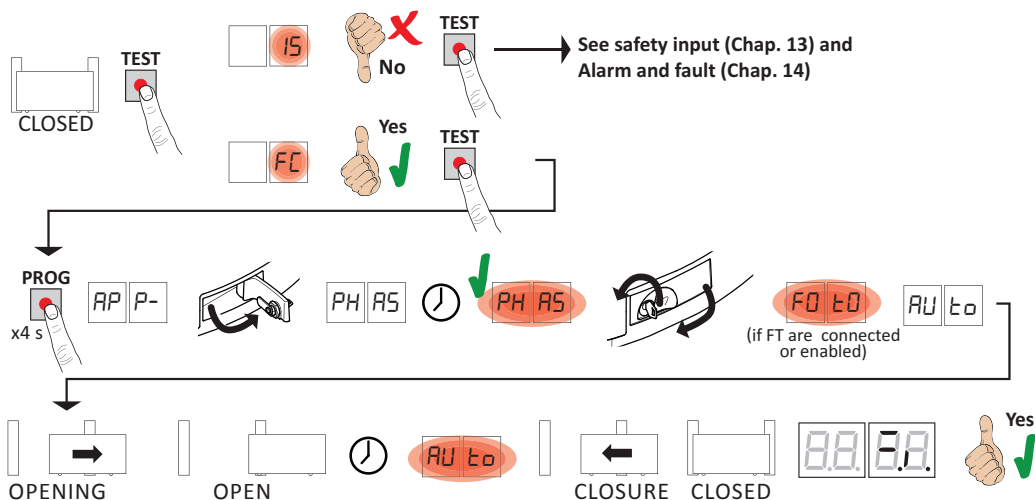
8 Travel acquisition

For the system to function correctly, the gate travel must be acquired by the control.

Before starting:

1. Select the position of the motor relative to the gate with the parameter $7\ I$. The default setting for this parameter is with the motor installed on the right hand side of the gate (seen from interior side).
2. Select the automation system model installed with the parameter $A\ I$. The default setting for this parameter is motor type BH30/600 or BH30/500/HS.
3. Check that the operator present function is not enabled ($A7\ 00$).
4. Move the gate into the closed position.
5. Press **TEST** (see TEST mode in chapter 7) and check the command signal and safety device states. If any safety devices are not installed, jumper the relative contact or disable the device from the relative parameter (50 , $5\ I$, 53 , 54 , 73 and 74).

ACQUISITION PROCEDURE:



- Press and hold **PROG** for 4 seconds. $AP\ P-$ is shown on the display.
- Open the release handle. The message $PH\ AS$ appears on the display after a few seconds. The controller unit launches a calibration procedure. The operating parameters of the motor are determined during calibration.
- If the motor calibration procedure is successful, the message $PH\ AS$ flashes on the display.
- Close the release handle. The acquisition procedure now starts.
- $FO\ t0$ is shown on the display (only if parameters 50 , $5\ I$, 53 , 54 are not disabled). Keep away from the photocell beam within 5 s, to prevent interrupting the procedure.
- $AU\ t0$ is shown on the display and the gate starts opening at low speed.
- The gate stops briefly when it reaches the gate open limit switch. $AU\ t0$ flashes on the display.
- The gate closes until it reaches the gate closed limit switch.

If the acquisition procedure is completed successfully, the display enters the command and safety device state display mode.

If the following error messages are shown on the display, repeat the acquisition procedure:

- $no\ PH$: calibration procedure failed.
- $AP\ PE$: acquisition error. Press the TEST button to clear the error, and check the safety device in alarm state.
- $AP\ PL$: travel length error. Press the TEST button to clear the error, and check that both gate leaves are completely closed.

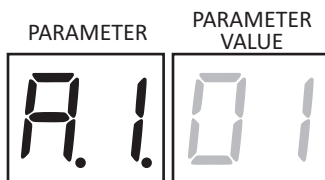
i For more information, see chapter 14 “Alarms and faults”.


9 Parameter's index

PARAM.	FACTORY VALUE	DESCRIPTION	PAGE
A1	01	Selecting automation system model	47
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A3	00	Automatic gate closing after mains power outage	47
A4	00	Selecting step mode control function (PP)	47
A5	00	Pre-flashing	47
A6	00	Condominium function for partial open command (PED)	48
A7	00	Enabling operator present function.	48
A8	00	Gate open indicator / photocell test function and "battery saving"	48
11	04	Setting deceleration during opening (and closing for BH30/600 - BH30/800)	48
12 	04	Setting deceleration during closing (BH30/500/HS only)	55
13	02	Setting gate open limit switch constant speed approach distance	48
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15	50	Partial opening adjustment (%)	48
21	30	Setting automatic closing time	48
27	03	Setting reverse time after activation of sensing edge or obstacle detection (crush prevention).	48
30	05	Setting motor torque	49
31	15	Setting obstacle impact force sensitivity	49
33	04	Setting start acceleration during opening (and closing for BH30/600 - BH30/800)	49
34 	04	Setting start acceleration during closing (BH30/500/HS only)	55
36	00	Enabling maximum torque boost at start of manoeuvre	49
37	00	Setting motor torque during position recovery	49
40	05	Setting opening speed (%) (and closing for BH30/600 - BH30/800)	49
41 	05	Setting closing speed (%) (BH30/500/HS only)	55
42	03	Setting end of manoeuvre constant approach speed	50
49	01	Setting number of automatic closure attempts after activation of sensing edge or obstacle detection (crush protection)	50
50	00	Setting photocell mode during gate opening (FT1)	50
51	02	Setting photocell mode during gate closing (FT1)	50
52	01	Photocell (FT1) mode with gate closed	50
53	00	Setting photocell mode during gate opening (FT2)	50
54	00	Setting photocell mode during gate closing (FT2)	51
55	01	Photocell (FT2) mode with gate closed	51
56	00	Enable close command 6 s after activation of photocell (FT1-FT2)	51
65	05	Setting motor stop distance	51
71	01	Selecting installation position of motor relative to gate (seen from interior side)	51
73	00	Configuring sensing edge COS1	51
74	00	Configuring sensing edge COS2	51

PARAM.	FACTORY VALUE	DESCRIPTION	PAGE
76	00	Configuring radio channel 1 (PR1)	52
77	01	Configuring radio channel 2 (PR2)	52
78	00	Configuring flashing light frequency	52
79	60	Selecting courtesy light mode	52
80	00	Clock contact configuration.	52
81	00	Enable safeguarded gate closure/opening.	52
82	03	Setting safeguarded closure/opening activation time	53
90	00	Restoring factory default values	53
n0	01	HW version.	53
n1	23	Year of manufacture	53
n2	45	Week of manufacture	53
n3	67	Serial number	53
n4	89		53
n5	01		53
n6	23	FW version	53
o7	01	View manoeuvre counter	54
o0	23		54
o1	45		54
h0	01	View manoeuvre hour counter	54
h1	23		54
d0	01	View control unit days on counter	54
d1	23		54
P1	00	Password	54
P2	00		54
P3	00		54
P4	00		54
CP	00	Changing password	54

10 Parameter menu



A1 01	Selecting automation system model
A1 03	WARNING! If this parameter is not set correctly, the automation system may not function properly. N.B.: in the event of a reset to restore the default parameters, this parameter must be set again manually.
01	BH30/600
02	BH30/800
03	BH30/500/HS  (see page. 55 of chapter 11 "Special parameters for High Speed series")

A2 00	Automatic closure after photocell is triggered (from gate completely open)
00	Disabled.
01-15	From 1 to 15 of gate closure attempts after photocell is triggered. Once the number of attempts set is reached, the gate remains open.
99	The gate tries to close indefinitely.

A3 00	Automatic gate closing after mains power outage
00	Disabled. The gate does not close automatically when mains power is restored.
01	Enabled. If the gate is NOT completely open, when mains power is restored, the gate closes after a 5 second warning signalled with the flashing light (independently of the value set with the parameter A5). The gate closes in "position recovery" mode (see chapter 17).

A4 00	Selecting step mode control function (PP)
00	Open-stop-close-stop-open-stop-close...
01	Condominium function: the gate opens and closes after the set automatic closing time. The automatic closing timer restarts if a new step mode command is received. Step mode commands are ignored while the gate is opening. This allows the gate to open completely and prevents the gate from closing when not required. If automatic closing is disabled (A2 00), the condominium function automatically attempts a closing manoeuvre A2 01.
02	Condominium function: the gate opens and closes after the set automatic closing time. The automatic closing timer does NOT restart if a new step mode command is received. Step mode commands are ignored while the gate is opening. This allows the gate to open completely and prevents the gate from closing when not required. If automatic closing is disabled (A2 00), the condominium function automatically attempts a closing manoeuvre A2 01.
03	Open-close-open-close.
04	Open-close-stop-open.

A5 00	Pre-flashing
00	Disabled. The flashing light is activated during opening and closing manoeuvres.
01-10	Flashing warning signal for 1 to 10 seconds prior to every manoeuvre.
99	5 second flashing warning signal prior to closing manoeuvre.

A6 00	Condominium function for partial open command (PED)
00	Disabled. The gate opens partially in step mode: open-stop-close-stop-open...
01	Enabled. Partial commands are ignored during gate opening.
A7 00	Enabling operator present function.
00	Disabled.
01	Enabled. The open (AP) or close (CH) button must be pressed continuously to operate the gate. The gate stops when the button is released.
A8 00	Gate open indicator / photocell test function and “battery saving”
00	The indicator is off when the gate is closed, and steadily lit during manoeuvres and when the gate is open.
01	The indicator flashes slowly during opening manoeuvres, and is lit steadily when the gate is completely open. It flashes quickly during closing manoeuvres. If the gate is stopped in an intermediate position, the lamp extinguishes twice every 15 seconds.
02	Set 02 if the output SC is used for the photocell test. See fig. 6.
03	Set to 03 if the output SC is used for the “battery saving” function. See fig. 7.
03	When the gate is completely open or closed, the controller unit deactivates any accessories connected to terminal SC to reduce battery consumption.
04	Set to 04 if the output SC is used for the “battery saving” function and photocell test function. See fig. 7.
11 04	Setting deceleration during opening and closing
01-05	01= the gate decelerates near the limit switch ... 05= the gate decelerates long before the limit switch.
13 02	Setting gate open limit switch constant speed approach distance N.B.: the manoeuvre speed is set with parameter 42. After decelerating, the gate completes the distance to the limit switch at constant speed.
14 02	Setting gate closed limit switch constant speed approach distance N.B.: the manoeuvre speed is set with parameter 42. After decelerating, the gate completes the distance to the limit switch at constant speed.
01-40	01 = last 4 motor revolutions; 02 = last 8 motor revolutions; ... 40 = last 160 motor revolutions. Example: 100 cm distance = value 35.
15 50	Partial opening adjustment (%) N.B.: This parameter is set to 50% (half of total gate travel) by default.
10-99	From 10% to 99% of total gate travel.
21 30	Setting automatic closing time The timer starts from the gate open state and continues for the set time. Once the set time is reached, the gate closes automatically. The timer count restarts if a photocell is triggered.
00-90	Pause time settable from 00 to 90 s.
92-99	Pause time settable from 2 to 9 min.
27 03	Setting reverse time after activation of sensing edge or obstacle detection (crush prevention). This sets the reverse manoeuvre time after activation of the sensing edge or the obstacle detection system.
00-60	From 0 to 60 s.

30 05	Setting motor torque Increasing or decreasing the value of the parameter increases or decreases motor torque and, as a result, adjusts obstacle detection sensitivity. Use values below 03 ONLY for particularly lightweight installations not exposed to severe weather conditions (strong winds or very cold temperatures).
01-09	01= -35%; 02= -25%; 03= -16%; 04= -8% (reduced motor torque = increased sensitivity). 05= default motor torque setting. 06= +8%; 07= +16%; 08= +25%; 09= +35% (increased motor torque = reduced sensitivity).
31 15	Setting obstacle impact force sensitivity If the reaction time to obstacle impact force is too long, reduce the value of the parameter. If the impact force exerted on obstacles is too high, reduce the value of parameter 30.
01-10	Low motor torque: 01 = minimum obstacle impact force ... 10 = maximum obstacle impact force N.B.: only use these settings if the medium motor torque values are not suitable for the installation.
11-16	Medium motor torque. Recommended setting for adjusting force settings correctly. 11 = minimum obstacle impact force ... 19 = maximum obstacle impact force.
17	70% of maximum motor torque, 1 s of reaction time. Sensing edge is compulsory.
18	80% of maximum motor torque, 2 s of reaction time. Sensing edge is compulsory.
19	Maximum motor torque, 3 s of reaction time. Sensing edge is compulsory.
20	Maximum motor torque, 5 s of reaction time. Sensing edge is compulsory.
33 04	Setting start acceleration during opening and closing
01-05	01= the gate accelerates rapidly at start of manoeuvre ... 05= the gate accelerates slowly and progressively at start of manoeuvre.
36 00	Enabling maximum torque boost at start of manoeuvre If this parameter is enabled, each time the motor starts a manoeuvre, maximum torque is produced for a maximum of 5 seconds, or for the time necessary for the gate to open by approximately 65 cm.
00	Disabled.
01	Enabled at start of opening manoeuvre only (including position recovery). The motor starting current function is only enabled for closing manoeuvres if the gate position is known and the gate is at least 2 metres from the completely closed position.
02	Enabled for all starts (including position recovery).
37 00	Setting motor torque during position recovery Adjust motor torque with parameter 37 if, during position recovery, the values set with parameters 30 and 31 are insufficient to allow the gate to complete the manoeuvre. If position recovery is not completed, normal gate operation will not be resumed.
00	The response of the obstacle detection system depends solely on the values set for parameters 30 and 31.
01	The response of the obstacle detection system depends on the values set for parameters 30 and 31 and on the maximum current value stored during travel acquisition.
02	The response of the obstacle detection system is a 70% reduction in maximum torque for a period of 1 s.
03	The response of the obstacle detection system is a 80% reduction in maximum torque for a period of 2 s.
04	The response of the obstacle detection system is a 100% reduction in maximum torque for a period of 3 s.
05	The response of the obstacle detection system is a 100% reduction in maximum torque for a period of 5 s.
40 05	Setting opening and closing speed (%)
01-05	01= 60% minimum speed, 02= 70%, 03= 80%, 04=90%, 05= 100% maximum speed.

42 03	Setting end of manoeuvre constant approach speed Once deceleration is complete, the gate continues to the limit switch at constant speed. The distance is set with the parameters <i>13</i> and <i>14</i> .
0 1- 10	01= 250 RPM 02= 300 RPM 03= 350 RPM 04= 400 RPM 05= 450 RPM 06= 500 RPM 07= 550 RPM 08= 600 RPM 09= 650 RPM 10= 700 RPM

49 01	Setting number of automatic closure attempts after activation of sensing edge or obstacle detection (crush protection)
00	No automatic closure attempts.
0 1- 03	From 1 to 3 automatic closure attempts. We recommend setting a value equal to or lower than the value set for parameter <i>R2</i> . Automatic closure is only performed if the gate is completely open.

50 00	Setting photocell mode during gate opening (FT1)
00	DISABLED. Photocell is not active or not installed.
0 1	STOP. The gate stops and remains stationary until the next command is received.
02	IMMEDIATE REVERSE. The gate reverses immediately if the photocell is activated during gate opening.
03	TEMPORARY STOP. The gate stops as long as the photocell is obstructed. The gate resumed opening when the photocell is cleared.
04	DELAYED REVERSE. The gate stops if the photocell is obstructed. The gate closes when the photocell is cleared.

51 02	Setting photocell mode during gate closing (FT1)
00	DISABLED. Photocell is not active or not installed.
0 1	STOP. The gate stops and remains stationary until the next command is received.
02	IMMEDIATE REVERSE. The gate reverses immediately if the photocell is activated during gate closure.
03	TEMPORARY STOP. The gate stops as long as the photocell is obstructed. The gate resumed closing when the photocell is cleared.
04	DELAYED REVERSE. The gate stops if the photocell is obstructed. The gate opens when the photocell is cleared.

52 01	Photocell (FT1) mode with gate closed
00	If the photocell is obstructed, the gate cannot open.
0 1	The gate opens when an open command is received, even if the photocell is obstructed.
02	The photocell sends the gate open command when obstructed.

53 00	Setting photocell mode during gate opening (FT2)
00	DISABLED. Photocell is not active or not installed.
0 1	STOP. The gate stops and remains stationary until the next command is received.
02	IMMEDIATE REVERSE. The gate reverses immediately if the photocell is activated during gate opening.
03	TEMPORARY STOP. The gate stops as long as the photocell is obstructed. The gate resumed opening when the photocell is cleared.
04	DELAYED REVERSE. The gate stops if the photocell is obstructed. The gate closes when the photocell is cleared.

54 00	Setting photocell mode during gate closing (FT2)
00	DISABLED. Photocell is not active or not installed.
01	STOP. The gate stops and remains stationary until the next command is received.
02	IMMEDIATE REVERSE. The gate reverses immediately if the photocell is activated during gate closure.
03	TEMPORARY STOP. The gate stops as long as the photocell is obstructed. The gate resumed closing when the photocell is cleared.
04	DELAYED REVERSE. The gate stops if the photocell is obstructed. The gate opens when the photocell is cleared.

55 01	Photocell (FT2) mode with gate closed
00	If the photocell is obstructed, the gate cannot open.
01	The gate opens when an open command is received, even if the photocell is obstructed.
02	The photocell sends the gate open command when obstructed.

56 00	Enable close command 6 s after activation of photocell (FT1-FT2)
This parameter is not visible if AB 03 or AB 04 is set.	
00	Disabled.
01	Enabled. When the photocell barrier FT1 is crossed, a close command is sent 6 seconds later.
02	Enabled. When the photocell barrier FT2 is crossed, a close command is sent 6 seconds later.

65 05	Setting motor stop distance
01-05	01= faster deceleration/shorter stop distance ... 05= slower deceleration/longer stop distance.

71 01	Selecting installation position of motor relative to gate (seen from interior side)
00	Motor installed on left.
01	Motor installed on right.

73 00	Configuring sensing edge COS1
00	Sensing edge NOT INSTALLED.
01	NC contact (normally closed). The gate reverses only when opening.
02	Contact with 8k2 resistor. The gate reverses only when opening.
03	NC contact (normally closed). The gate always reverses.
04	Contact with 8k2 resistor. The gate always reverses.

74 00	Configuring sensing edge COS2
00	Sensing edge NOT INSTALLED.
01	NC contact (normally closed). The gate reverses only when closing.
02	Contact with 8k2 resistor. The gate reverses only when closing.
03	NC contact (normally closed). The gate always reverses.
04	Contact with 8k2 resistor. The gate always reverses.

76 00	Configuring radio channel 1 (PR1) N.B.: With ROGER TECHNOLOGY plug-in radio receiver board.
77 01	Configuring radio channel 2 (PR2) N.B.: With ROGER TECHNOLOGY plug-in radio receiver board.
00	STEP MODE.
01	PARTIAL OPENING
02	OPENING
03	CLOSING.
04	STOP.
05	Courtesy light. The output COR is managed from the remote control. The light remains lit as long as the remote control is active. The parameter 79 is ignored.
06	Courtesy light in step mode (PP). The output COR is managed from the remote control. The remote control turns the courtesy light on and off. The parameter 79 is ignored.
07	STEP MODE with confirmation for safety. ⁽¹⁾
08	PARTIAL OPENING with confirmation for safety. ⁽¹⁾
09	OPENING with confirmation for safety. ⁽¹⁾
10	CLOSURE with confirmation for safety. ⁽¹⁾

⁽¹⁾ To prevent gate manoeuvres caused by accidentally pressing a remote control button, confirmation is required to enable the command.

Example: parameters 76 07 and 77 01 set:

- Pressing the CHA button on the remote control selects the step mode function, which must be confirmed within 2 seconds by pressing CHB on the remote control. Press CHB to activate partial opening.

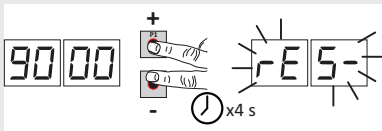
78 00	Configuring flashing light frequency
00	The frequency is set electronically from the flashing light unit.
01	Slow flash.
02	Light flashes slowly when gate opens, rapidly when gate closes.

79 60	Selecting courtesy light mode
00	Disabled.
01	PULSE. The courtesy light illuminates briefly at the start of each manoeuvre.
02	ACTIVE. The light remains lit for the entire duration of the manoeuvre.
03-90	From 3 to 90 s. The light remains lit for the time period set after the manoeuvre is completed.
92-99	From 2 to 9 minutes. The light remains lit for the time period set after the manoeuvre is completed.

80 00	Clock contact configuration. When the clock function is active, the gate opens and remains open. At the end of the programmed time set with the external device (clock), the gate closes.
00	When the clock function is active, the gate opens and remains open. Any command signal received is ignored.
01	When the clock function is active, the gate opens and remains open. Any command signal received is accepted. When the gate returns to the completely open position, the clock function is reactivated.

B1 00	Enable safeguarded gate closure/opening. Enabling this parameter ensures that the gate is not left open due to an incorrect and/or accidental command. This function is <u>NOT</u> enabled if: <ul style="list-style-type: none"> the gate receives a STOP command; the sensing edge is activated; the number of closure attempts set by parameter <i>B2</i> has been reached; the acquired position is lost (perform position recovery, see chapter 17).
00	Disabled. The parameter <i>B2</i> is not displayed.
01	Enabled. After a period of time set with parameter <i>B2</i> , the control unit signals a 5 second warning with the flashing light, regardless of the parameter <i>B5</i> , and then closes the gate.
02	Enabled. If the gate is closed as a result of a step mode command, after a period of time set with parameter <i>B2</i> , the control unit signals a 5 second warning with the flashing light (regardless of the parameter <i>B5</i>), and then the gate closes. If the gate is stopped by the obstacle detection system during a closure manoeuvre, the gate closes after a period of time set with parameter <i>B2</i> . If the gate is stopped by the obstacle detection system during an opening manoeuvre, the gate closes after a period of time set with parameter <i>B2</i> .

B2 03	Setting safeguarded closure/opening activation time N.B.: this parameter is not visible if the value of parameter <i>B1</i> = 00.
02-90	Wait time settable from 2 to 90 s.
92-99	Wait time settable from 2 to 9 min.

90 00	Restoring factory default values NOTE This procedure is only possible if NO data protection password is set.
 <p>Warning! Restoring default settings cancels all settings made previously except for parameter <i>B1</i> : after restore, check that all parameters are suitable for the installation.</p> <p>The default factory settings may also be restored using the UP ▲ and/or DOWN ▼ buttons as follows:</p> <ul style="list-style-type: none"> Turn off the power. Press and hold the UP ▲ and DOWN ▼ button until the unit switches on. The display flashes after 4 s <i>FE5-</i>. The default factory settings have now been restored. 	

Identification number The identification number consists of the values of the parameters from <i>n0</i> to <i>n5</i> . N.B.: The values shown in the table are indicative only.	
n0 01	HW version.
n1 23	Year of manufacture.
n2 45	Week of manufacture.
n3 67	Example: 01 23 45 67 89 01 23
n4 89	
n5 01	
n6 23	

	View manoeuvre counter The number consists of the values of the parameters from $\alpha 1$ to $\alpha 4$ multiplied by 100. N.B.: The values shown in the table are indicative only.
$\alpha 1$ 01	
$\alpha 2$ 23	Manoeuvres performed. Example: $01\ 23\ 45 \times 100 = 1.234.500$ manoeuvres.
$\alpha 4$ 45	
	View manoeuvre hour counter The number consists of the values of the parameters from $h 0$ to $h 1$. N.B.: The values shown in the table are indicative only.
$h 0$ 01	Manoeuvre hours. Example: $01\ 23 = 123$ hours.
$h 1$ 23	
	View control unit days on counter The number consists of the values of the parameters from $d 0$ to $d 1$. N.B.: The values shown in the table are indicative only.
$d 0$ 01	Days with unit switched on. Example: $01\ 23 = 123$ days.
$d 1$ 23	
	Password Setting a password prevents unauthorised persons from accessing the settings. With password protection active ($CP=01$), parameters may be viewed, but the values CANNOT be modified. <u>Only a single password is used to control access to the gate automation system.</u> WARNING: Contact the Technical Support Service if you lose your password.
$P1$ 00 $P2$ 00 $P3$ 00 $P4$ 00	Password activation procedure: <ul style="list-style-type: none"> • Enter the desired values for parameters $P1$, $P2$, $P3$ and $P4$. • Use the UP ▲ and/or DOWN ▼ buttons to view the parameter CP. • Press and hold the + and - buttons for 4 seconds. • The display flashes to confirm that the password has been saved. • Switch the control unit off and on again. Check that password protection is activated ($CP=01$).
	Temporary unlock procedure: <ul style="list-style-type: none"> • Enter the password. • Check that $CP=00$.
	Password cancellation procedure: <ul style="list-style-type: none"> • Enter the password ($CP=00$). • Save the values $P1$, $P2$, $P3$, $P4 = 00$ • Use the UP ▲ and/or DOWN ▼ buttons to view the parameter CP. • Press and hold the + and - buttons for 4 seconds. • The display flashes to confirm that the password has been cancelled (the values $P1\ 00$, $P2\ 00$, $P3\ 00$ and $P4\ 00$ indicate that no password is set). • Switch the control unit off and on again.
CP 00	Changing password
00	Protection deactivated.
01	Protection activated.

11 Special parameters for BH30/500/HS series



The BH30/HS series (High Speed) is a family of digital brushless high speed sliding motor units for sliding gates weighing up to 500 Kg and dedicated exclusively to residential applications.

High Speed technology makes it possible for the automation system to operate 100% faster than a conventional system, and allows independent management of speed, acceleration, deceleration and the safety devices used in the system.

The additional parameters for enabling High Speed technology are indicated as follows.

A103	Selecting automation system model This parameter is factory configured by ROGER TECHNOLOGY. WARNING! The parameter is already configured by default to enable use of the of motor in high speed mode. If this parameter is modified, all the specific motor functions relative to high speed mode will no longer be available. The automation system will no longer function effectively and it will not be possible to diagnose faults. N.B.: in the event of a reset to restore the default parameters, this parameter must be set again manually.
01	BH30/600
02	BH30/800
03	BH30/500/HS

1104	Setting deceleration during opening
1204	Setting deceleration during closing
01-05	01= the gate decelerates near the limit switch ... 05= the gate decelerates long before the limit switch.

3304	Setting start acceleration during opening
3404	Setting start acceleration during closing
01-05	01= the gate accelerates rapidly at start of manoeuvre ... 05= the gate accelerates slowly and progressively at start of manoeuvre.

4005	Setting opening speed (%)
4105	Setting closure speed (%)
01-05	01= 60% minimum speed 02= 70% 03= 80% 04= 90% 05= 100% maximum speed.



N.B.: to set the constant speed deceleration space, see parameters 13 and 14 on page 48.

12 Commands and Accessories

















If not installed, safety devices with NC contacts must be jumpered at the COM terminals, or disabled by modifying the parameters *50*, *51*, *53*, *54*, *73* and *74*.

KEY:

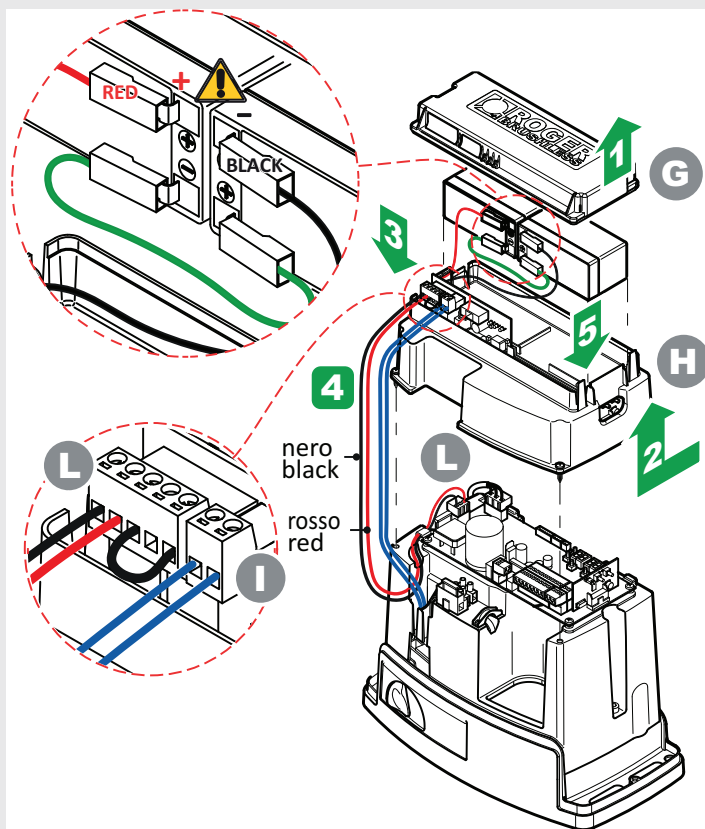
N.A. (Normally Open) .

N.C. (Normally Closed).

CONTACT	DESCRIPTION
6  7(COR)	Output (potential free contact) for connecting courtesy light. 230 Vac 100 W - 24 Vac/dc 40 W (fig. 4).
8(+SC)  9(COM)	Connection for gate open indicator lamp. 24 Vdc 3 W. The function of the indicator lamp is determined by parameter <i>AB</i> .
8(+SC) 9(COM)	Photocell test connection and/or battery saving. The power feed for the photocell transmitters (TX) may be connected to this. Set the parameter <i>AB 02</i> to enable the test function. Each time a command is received, the control unit switches the photocells off and on to check that the contact changes state correctly. Power feeds for all external devices may be connected to reduce battery consumption (if batteries are used). Set <i>AB 03</i> or <i>AB 04</i> . WARNING! If contact 8-SC is used for the photocell test function or battery saving function, a gate open indicator lamp cannot be connected.
10(FT2)  28(COM)	Input (NC) for connecting photocells FT2 (fig. 5, 6 and 7). The photocells FT2 are configured by default with the following settings: <ul style="list-style-type: none"> – <i>53 00</i> . Photocell FT2 disabled when gate is opening. – <i>54 00</i> . Photocell FT2 disabled when gate is closing. – <i>55 01</i> . The gate opens when an open command is received if photocell FT2 is obstructed. If the photocells are not installed, jumper the terminals 28(COM) - 10(FT2) or set the parameters <i>53 00</i> and <i>54 00</i> . WARNING! Use R90/F4ES , G90/F4ES or T90/F4S series photocells.
11(FT1)  28(COM)	Input (NC) for connecting photocells FT1 (fig. 5, 6 and 7). The photocells FT1 are configured by default with the following settings: <ul style="list-style-type: none"> – <i>50 00</i> . Photocell triggers only during gate closure. Photocell is ignored during gate opening. – <i>51 02</i> . Movement is reversed if the photocell is triggered during gate closure. – <i>52 01</i> . The gate opens when an open command is received if photocell FT1 is obstructed. If the photocells are not installed, jumper the terminals 28(COM) - 11(FT1) or set the parameters <i>50 00</i> and <i>51 00</i> . WARNING! Use R90/F4ES , G90/F4ES or T90/F4S series photocells.
12(COS2)  14(COM)	Input (NC or 8 kOhm) for connecting sensing edge COS2 . The sensing edge is configured by default with the following settings: <ul style="list-style-type: none"> – <i>74 00</i> . The sensing edge COS2 (NC contact) is disabled. If the sensing edge is not installed, jumper the terminals 12(COS2) - 14(COM) or set the parameter <i>74 00</i> .
13(COS1)  14(COM)	Input (NC or 8 kOhm) for connecting sensing edge COS1 . The sensing edge is configured by default with the following settings: <ul style="list-style-type: none"> – <i>73 00</i> . The sensing edge COS1 (NC contact) is disabled. If the sensing edge is not installed, jumper the terminals 13(COS1) - 14(COM) or set the parameter <i>73 00</i> .
15(ST)  14(COM)	STOP command input (NC). The current manoeuvre is arrested if the safety contact opens. N.B.: jumper the contact if it is not used.
20  19(ANT)	Antenna connector for slot-in radio receiver board. Use RG58 if an external antenna is used; maximum recommended length: 10 m. N.B.: do not make joints in cable.

CONTACT	DESCRIPTION
22(ORO) 21(COM) 	Clock timer contact input (N.O.). When the clock function is active, the gate opens and remains open. At the end of the programmed time set with the external device (clock), the gate closes.
23(AP) 21(COM) 	Open control signal input (N.O.).
24(CH) 21(COM) 	Close command input (N.O.).
25(PP) 21(COM) 	Step by step mode command input (N.O.). The function of the control is determined by parameter <i>PR4</i> .
26(PED) 21(COM) 	Partial open control signal input (N.O.). Set by default to 50% of completely open position.
27(+24V) 28(COM)	Power feed for external devices. See technical characteristics.
29(LAM) 28(COM) 	Connection for flashing light (24 Vdc - duty cycle 50%). The settings for the pre-manoeuve flashing warning signal may be selected with parameter <i>PR5</i> , while the flashing mode is set with parameter <i>TR8</i> .
ENC	Connector for connecting to encoder installed on motor. WARNING! Always disconnect from electrical power before disconnecting or connecting the encoder cable. N.B.: Ready wired in factory by ROGER TECHNOLOGY.
FC	Connector (N.C. contacts) for connecting mechanical limit switch (see figure 10 - detail E) or magnetic limit switch (see figure 10 - detail F). The gate stops when the limit switch is activated. N.B.: Ready wired in factory by ROGER TECHNOLOGY.
SB	Connector (N.C.) for connecting release contact. If the motor release handle is opened, the gate stops and no command signals are accepted. Once the release handle is closed again, if the gate is in an intermediate position, the controller unit initiates the position recovery procedure (see chapter 17). N.B.: Ready wired in factory by ROGER TECHNOLOGY.
RECEIVER CARD	Connector for plug-in radio receiver board. The control unit has two radio remote control functions by default: <ul style="list-style-type: none"> – PR1 - step mode command (modifiable with parameter <i>TR5</i>). – PR2 - partial opening command (modifiable with parameter <i>TR7</i>). The programming buttons PR1 and PR2 are also accessible with the cover closed (see figure 8).
BATTERY CHARGER B71/BC	In the event of a mains power loss, the controller unit is powered by the batteries. When battery power is used, <i>bATT</i> is shown on the display and the flashing light flashes briefly at intervals until mains power is restored or until the battery voltage drops below the minimum permissible limit. In this case, <i>bELL</i> (Battery Low) is shown on the display and the controller unit accepts no commands. WARNING! the batteries must always be connected to the electronic controller unit in order to charge. Periodically (at least every 6 months), check that the battery is in good working order.
2x12 Vdc 1,2 Ah. or 2x12 Vdc 4,5 Ah Only AGM type	Two battery kits are available: <ul style="list-style-type: none"> • Two 12 V DC, 1.2 Ah batteries installed in the automation system itself. • Two 12 V DC, 4.5 Ah batteries installed in an external case. For more information, refer to the installation manual for the B71/BC battery charger.

CONTACT	DESCRIPTION
BATTERY CHARGER B71/BC 2x12 Vdc 1,2 Ah.	<p>To install the battery charger and the 12 V DC, 1,2 Ah batteries:</p> <ul style="list-style-type: none"> • Remove the upper cover G. • Remove the cover H. • Install the B71/BC battery charger board in the relative seat. • Disconnect the wires from the transformer and from the POWER IN terminal of the controller unit, and connect them to terminal I of the battery charger. • Connect the red-black wires of cable L included with the battery to the POWER IN terminal of the controller unit. • Close the cover H and fasten with the screws. • Fit the 12 V DC 1.2 Ah batteries in the relative compartment, ensuring that the polarity is correct. • Close the upper cover G.



To reduce battery consumption, the positive power feed wire of the photocell transmitters may be connected to terminal **SC** (see fig. 6-7). Set **AB 03** or **AB 04**. In this configuration, the controller unit disconnects power from the accessory devices when the gate is completely open or completely closed.

13 Safety input and command status (TEST mode)

With no currently active commands, press the TEST button and check the following:

DISPLAY	POSSIBLE CAUSE	ACTION BY SOFTWARE	PHYSICAL CORRECTIVE ACTION
88 5b(Sb)	The release handle is open.	-	Close the release handle and turn the key to the close position. Check that the release contact is connected correctly.
88 15	The safety STOP contact is open.	-	Install a STOP button (NC) or jumper the ST contact with the COM contact.
88 13	Sensing edge COS1 not connected or incorrectly connected.	Set the parameter 73 00 if not used or to disable	Jumper contact COS1 with contact COM, if not used or to disable
88 12	Sensing edge COS2 not connected or incorrectly connected.	Set the parameter 74 00 if not used or to disable	Jumper contact COS2 with contact COM, if not used or to disable
88 11	Photocell FT1 not connected or incorrectly connected.	Set the parameter 50 00 e 54 00 if not used or to disable	Jumper contact FT1 with contact COM, if not used or to disable. Check connection referring to relative connection diagram (figures 6-7).
88 10	Photocell FT2 not connected or incorrectly connected.	Set the parameter 53 00 e 54 00 if not used or to disable	Jumper contact FT2 with contact COM, if not used or to disable. Check connection referring to relative connection diagram (figures 6-7).
88 FE	Both limit switches in open contact state or not connected.	-	Check connection of limit switches.
88 FA	Gate is at gate closed limit switch.	If the limit switch state indicated is incorrect, check the setting of parameter 7 l.	-
	Gate open limit switch absent or not connected.	-	Check connection of limit switches.
88 FC	Gate is at gate closed limit switch.	If the limit switch state indicated is incorrect, check the setting of parameter 7 l.	-
	Gate closed limit switch absent or not connected.	-	Check connection of limit switches.
PP 00	If occurs with no voluntary command, the contact (N.O.) may be faulty or one of the buttons may be incorrectly connected.	-	Check PP - COM contacts and connections to buttons.
CH 00		-	Check CH - COM contacts and connections to buttons.
AP 00		-	Check AP - COM contacts and connections to buttons.
PE 00		-	Check PED - COM contacts and connections to buttons.
OR 00	If occurs with no voluntary command, the contact (N.O.) may be faulty or the timer may be incorrectly connected.	-	Check ORO - COM contacts. Contact must not be jumpered if not used.

N.B.: We recommend troubleshooting safety device and input status errors with “corrective action by software” only.

14 Alarms and faults

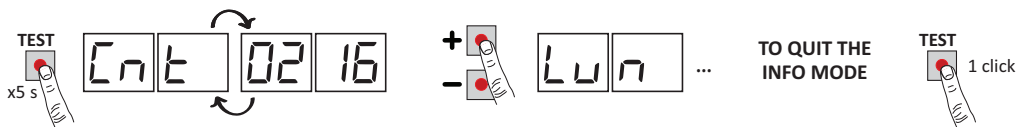
PROBLEM	ALARM	POSSIBLE CAUSE	ACTION
The gate does not open or close.	POWER LED off	No power.	Check power cable.
	POWER LED off	Fuses blown.	Replace fuses. Always disconnect from mains power before removing fuses.
	<i>OF St</i>	Input mains power voltage fault. Control initialisation failed.	Disconnect from mains power, wait 10 seconds then reconnect to the mains and switch on. We recommend replacing the control unit if the problem persists.
	<i>Pr Ot</i>	Overcurrent detected in inverter.	Press the TEST button twice or perform 3 command requests in succession.
	<i>dAtA</i>	Incorrect travel length values.	Repeat acquisition procedure.
	<i>Not</i>	Motor not connected.	Check the motor cable.
	<i>FE</i>	Both limit switches activated.	Check connections of limit switches or check for foreign objects in limit switch blocks.
	Example: <i>15 EE</i> <i>21 EE</i>	Configuration parameter error.	Set configuration value correctly and save.
	<i>EnE 1</i>	Encoder not connected.	Check connection to encoder. Replacing the encoder is recommended if the problem persists.
	<i>EnE3</i>	Severe encoder malfunction.	Press TEST button. If the error code is displayed again, switch off the controller unit, wait 5 seconds and switch on again. Replace the encoder if the problem persists.
	<i>EnE5 (EnE5)</i>	Encoder malfunction.	Press TEST button. Replace the encoder if the problem persists.
		Insufficient power supply	If the unit contains dirt, moisture, insects or other foreign matter, disconnect from mains power and clean the board and the encoder. Replace the encoder if the problem persists.
		Batteries functioning	The batteries are almost flat.
	<i>EnE8</i>	Encoder calculation error.	Repeat acquisition procedure.
	<i>tENP</i>	Inverter thermal overload circuit breaker tripped.	Function is restored automatically within 2 min.
Acquisition procedure does not complete correctly.	<i>btLO (btLO)</i>	Flat batteries.	Wait for mains power to be restored.
	<i>Stop</i> flashing	Release device open.	Close the release handle and turn the key to the close position. Check that the release contact is connected correctly.
	<i>no PH</i>	Motor calibration failed.	Repeat acquisition procedure. If the problem persists, check the cable connecting the encoder to the motor. Check if release handle is open. Check that the motor turns without impediment. Contact technical support in case of any problems.
	<i>AP PE</i>	TEST button pressed accidentally. Safety devices in alarm state. Excessive voltage drop.	Repeat acquisition procedure. Check connections of safety devices. Repeat acquisition procedure. Check mains voltage.
	<i>AP PL</i>	Travel length error.	Move gate into completely closed position (FC limit switch signal must be active) and repeat the procedure. Check cable of limit switches. Replace the cable if the problem persists. Reset default controller unit parameters and repeat the procedure.
Remote control has limited range and does not work while automated gate is moving.	-	The radio transmission is impeded by metal structures and reinforced concrete walls.	Install the antenna outside.
	-	Flat batteries.	Replace the transmitter batteries.

PROBLEM	ALARM	POSSIBLE CAUSE	ACTION
The flashing light is not working.	-	Bulb / LED blown or flashing light wires disconnected.	Check LED circuit and/or connector wires.
Gate open indicator lamp does not work.	-	Bulb blown or wires disconnected.	Check the bulb and/or wires.
Gate does not perform desired manoeuvre.	-	Incorrect setting of parameter 7 l.	Select the correct installation position with parameter 7 l.

N.B.: Press the TEST button to temporarily cancel the alarm.

The next time a command is received, the alarm reappears on the display if the problem has not been resolved.

15 Procedural verifications - INFO Mode



INFO mode may be used to view certain parameters measured by the **B70/1DC** controller.

Press and hold the TEST button for 5 seconds from the “View command signals and safety devices” mode with the motor stationary.

The control unit displays the following parameters and the corresponding measured values in sequence:

Parameter	Function
b 1.40	View for 3 s the firmware version of the control unit.
CnL	Displays the position of MOTOR, expressed in revolutions and relative to total length, at the time of the test. (example: 0.113 = motor installed on the left 7 l 00; 0.113 = motor installed on the right 7 l 0 l).
LUN	View total length of programmed travel of MOTOR, in motor revolutions.
rPM	View motor speed of MOTOR, in revolutions per minute (rpm).
AMP	View current absorption of motor, in Amperes (e.g.: 001.1 = 1,1 A ... 016.5 = 16,5 A). If the MOTOR is stationary, the current absorption value is 0. Activate a command function to test current absorption.
bUS	System OK indicator. To check for overloading (e.g.: too many utilities connected to 24 V output) or if the mains voltage is too low, compare the parameters read with values indicated as follows with the motor stationary: mains voltage = 230 V AC (nominal), bUS= 28.5 mains voltage = 207 V AC (-10%), bUS= 25.5 mains voltage = 253 V AC (+10%), bUS= 31.6
CNP	Display current, expressed in Amperes, used to compensate for strain detected by MOTOR due, for example, to low external temperatures (e.g.: 0 = 0 A ... 4 = +6 A). At the beginning of a manoeuvre from the completely open or completely closed position, if the control unit detects a strain higher than the value stored in its memory during the travel acquisition cycle, the controller automatically increases the current delivered to MOTOR.
ASC	Display current threshold, expressed in Amperes, at which the obstacle detection function (crush prevention) of MOTOR is triggered. This value is calculated automatically by the controller in relation to the settings of parameters 30 and 3 l. For the motor to function correctly, AMP must always be lower than the value ASC.
tIn	Indicates time taken by MOTOR to detect an obstacle, as set with parameter 3 l, in seconds. E.g. 1.000 = 1 s / 0.120 = 0.12 s (120 ms). Ensure that the manoeuvre time is more than 0.3 s.
UP	If the control unit is capable of identifying the position of the gate when the test is conducted, the following is shown on the display: UP_ position known, normal operation. UP_L position unknown, position recovery in progress.
OC	Indicates the state of the automation system (open/closed). OC OP automation system opening (motor active). OP CL automation system closing (motor active). OP -O automation system completely open (motor not active). OP -C automation system completely closed (motor not active).
UF	UF U mains voltage too low or overload. UF H motors overcurrent.

- Use the + / - buttons to scroll through the parameters. When the last parameter in the sequence is reached, press the - button to return through the previous parameters.
- In INFO mode, the automation system may be activated to test operation in real time.
- Press and hold the TEST button for a few seconds to exit INFO mode.

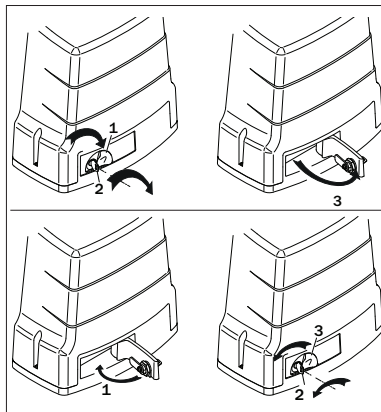
16 Mechanical release

In the event of a power failure, the gate may be released as follows.
If the gate releases with the controller unit powered, the message *5tOP* flashes on the display.

- Flip open the lock cover (1).
- Insert the key included into the lock and turn clockwise by 90° (2).
- Open the release cover completely (3).
- Move the gate manually.

RESTORING AUTOMATIC OPERATION

- Close the release cover with the key inserted, taking care not to trap your fingers (1).
- Turn the key anticlockwise by 90° (2).
- Remove the key and close the lock cover (3).
- When the release system is restored to the normal operating position, if the gate is not completely open or completely closed the next time a command is received, the control initiates a position recovery procedure (see chapter 17).
- Activating one of the two limit switches immediately reacquires the position.



17 Position recovery mode

After a mains power outage or after mechanically releasing the gate, if the gate is not completely open or completely closed the next time a command is received, the control initiates a position recovery procedure:

- The gate starts a low speed manoeuvre.
- The flashing light flashes with a different duty cycle than normal (3 s on, 1.5 s off).
- The control unit recovers the installation data during this procedure. **Warning!** During this procedure, do not use any controls until one of the two limit switches is reached.
- Activating one of the two limit switches immediately reacquires the position.

18 Initial testing

- Turn on the power supply.
- Check that all connected controls are working correctly.
- Check that the release handle works correctly. The message *5tOP* must flash on the display.
- Check travel and deceleration.
- Check that the impact force is correct, in compliance with EN 12453 and EN12445.
- Check that the safety devices are activated correctly.
- If the battery kit is installed, disconnect from mains and check that the batteries are working.
- Disconnect from mains power and disconnect the batteries (if used), then reconnect. Starting with the gate stopped in an intermediate position, check that the position recovery procedure is completed correctly for both the open and closed positions.
- Check the limit switch settings.

19 Maintenance

Perform scheduled maintenance every 6 months.

Check cleanliness and function.

If the unit contains dirt, moisture, insects or other foreign matter, disconnect from mains power and clean the board and the housing.

Repeat the initial installation test procedure after cleaning.

If any corrosion is found on the printed circuit board, evaluate if it is necessary to replace the board itself.

Check that the battery is in good working order.

20 Disposal

This product may only be uninstalled by qualified technical personnel, following suitable procedures for removing the product correctly and safely. This product consists of numerous different materials. Some of these materials may be recycled, while others must be disposed of correctly at the specific recycling or waste management facilities indicated by local legislation applicable for this category of product.



Do not dispose of this product as domestic refuse. Observe local legislation for differentiated refuse collection, or hand the product over to the vendor when purchasing an equivalent new product.

Local legislation may envisage severe fines for the incorrect disposal of this product.

Warning! Some parts of this product may contain substances that are harmful to the environment or dangerous and which may cause damage to the environment or health risks if disposed of incorrectly.

21 Additional information and contact details

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This instruction manual and the warnings for the installer are given in printed form and included in the box containing the product.

The digital version of this documentation (in PDF format) and all future revisions are available from the reserved area of our website **www.rogertechnology.com/B2B**, in the section 'Self Service'.

ROGER TECHNOLOGY CUSTOMER SERVICE:

business hours: Monday to Friday
08:00 to 12:00 - 13:30 to 17:30
Telephone no: +39 041 5937023
E-mail: service@rogertechnology.it
Skype: service_rogertechnology

To request support for any problems or for any other queries regarding the automation system, please compile the online form "REPAIRS" in the 'Self Service' area of our website **www.rogertechnology.com/B2B**.

22 Declaration of Conformity

I the undersigned, as acting legal representative of the manufacturer

Roger Technology - Via Botticelli 8, 31021 Bonisiolo di Mogliano V.to (TV)

hereby DECLARE that the appliance described below:

Description: Controller unit for automatic gates

Model: **B70/1DC**

Is conformant with the legal requisites of the following directives:

- 2006/42/EC
- 2004/108/CE
- 2011/65/EC

and that all the standards and/or technical requirements indicated as follows have been applied:

EN 61000-6-3

EN 61000-6-2

Last two figures of year in which marking was applied C€ 14.

Place: Mogliano V.to

Date: 23-12-2014

Signature